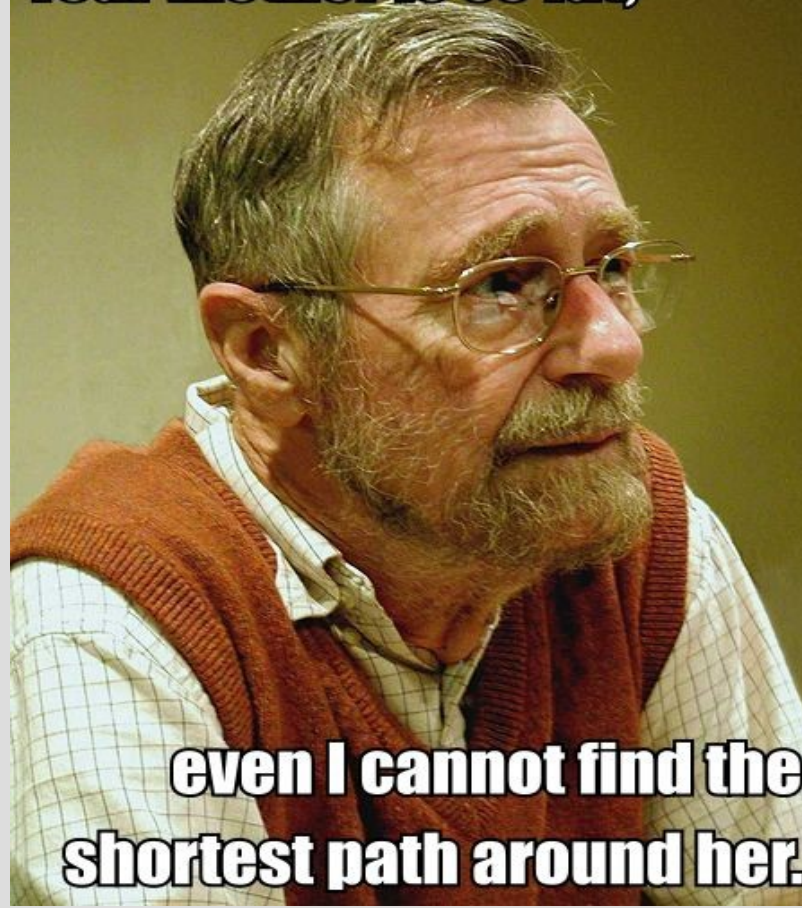


Weighted graphs

Your mother is so fat,



**even I cannot find the
shortest path around her.**

Weighted graph

Edges in weighted graph are assigned a weight: $w(v_1, v_2)$, where v_1, v_2 in V

If path $p = \langle v_0, v_1, \dots, v_k \rangle$ then the weight is: $w(p) = \sum_{i=1}^k w(v_{i-1}, v_i)$

Shortest Path:

$\delta(u, v) = \min\{w(p) : v_0 = u, v_k = v\}$

Shortest paths

Today we will look at single-source shortest paths

This finds the shortest path from some starting vertex, s , to any other vertex on the graph (if it exists)

This creates G_π , the shortest path tree

Shortest paths

Optimal substructure: Let $\delta(v_0, v_k) = p$, then for all $0 \leq i \leq j \leq k$, $\delta(v_i, v_j) = p_{i,j} = \langle v_i, v_{i+1}, \dots, v_j \rangle$

Proof?

Where have we seen this before?

Shortest paths

Optimal substructure: Let $\delta(v_0, v_k) = p$, then for all $0 \leq i \leq j \leq k$, $\delta(v_i, v_j) = p_{i,j} = \langle v_i, v_{i+1}, \dots, v_j \rangle$

Proof? Contradiction!

Suppose $w(p'_{i,j}) < p_{i,j}$, then let

$p'_{0,k} = p_{0,i} p'_{i,j} p_{j,k}$ then $w(p'_{0,k}) < w(p)$

Shortest path

We will do the same thing we have done before with BFS and DFS:

Makes a queue and put in/pull out

Two major differences:

- (1) How to remove from queue (min)
- (2) Update “grey” vertexes (“relax”)

Relaxation

We will only do relaxation on the values $v.d$ (min weight) for vertex v

$\text{Relax}(u, v, w)$  (i.e. $\text{min}()$ function)

if($v.d > u.d + w(u, v)$)

$v.d = u.d + w(u, v)$

$v.\pi = u$

Relaxation

We will assume all vertices start with $v.d = \infty, v.\pi = \text{NIL}$ except $s, s.d = 0$

This will take $O(|V|)$ time

This will not effect the asymptotic runtime as it will be at least $O(|V|)$ to find single-source shortest path

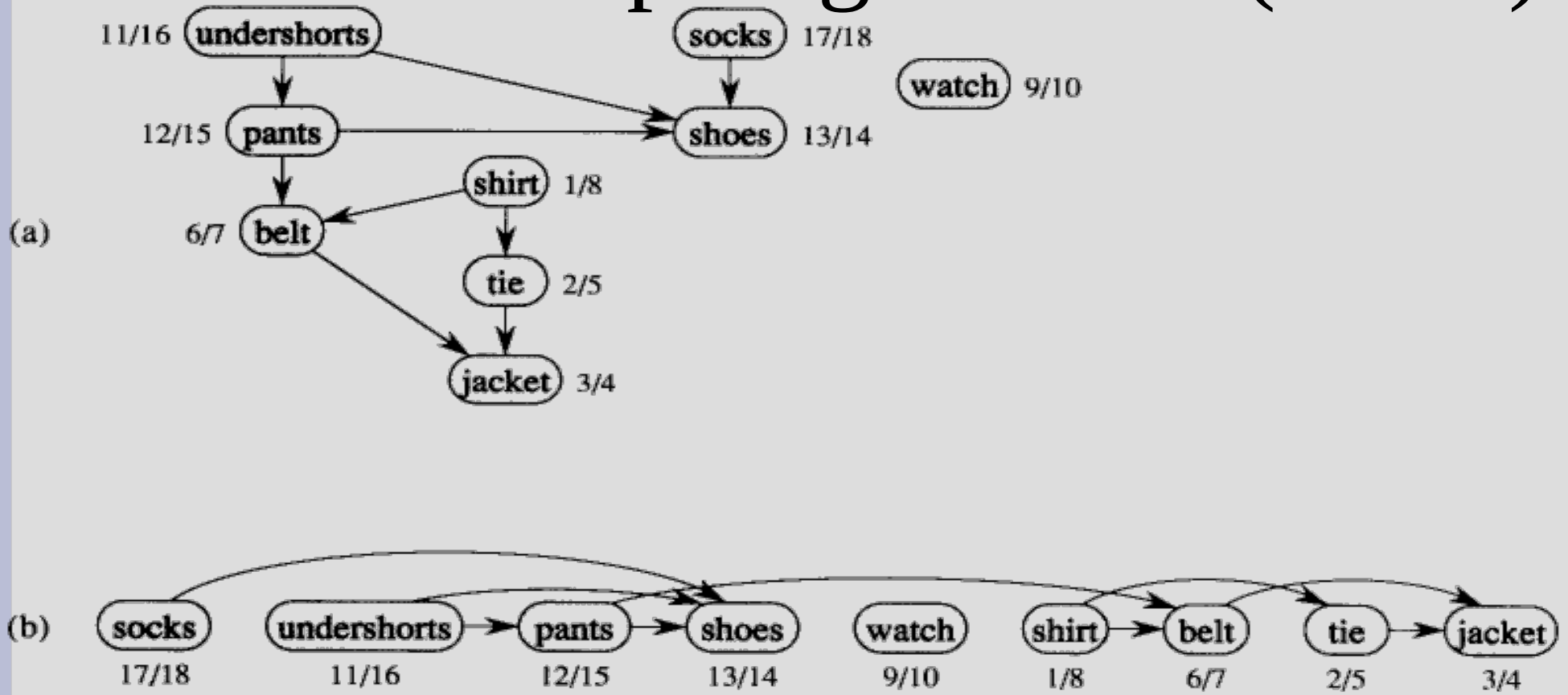
Relaxation

Relaxation properties:

1. $\delta(s,v) \leq \delta(s,u) + \delta(u,v)$ (triangle inequality)
2. $v.d \geq \delta(s,v)$, $v.d$ is monotonically decreasing
3. if no path, $v.d = \delta(s,v) = \infty$
4. if $\delta(s,v)$, when $(v.\pi).d = \delta(s,v.\pi)$ then $\text{relax}(v.\pi, v, w)$ causes $v.d = \delta(s,v)$
5. if $\delta(v_0, v_k) = p_{0,k}$, then when relaxed in order $(v_0, v_1), (v_1, v_2), \dots, (v_{k-1}, v_k)$ then $v_k.d = \delta(v_0, v_k)$ even if other relax happen
6. when $v.d = \delta(s,v)$ for all v in V , G_π is shortest path tree rooted at s

Directed Acyclic Graphs

DFS can do topological sort (DAG)



Run DFS, sort in decreasing finish time

Directed Acyclic Graphs

DAG-shortest-paths(G, w, s)

topologically sort G

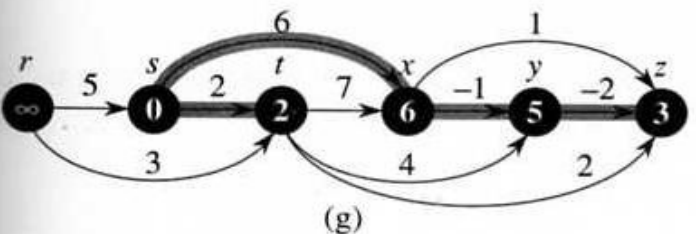
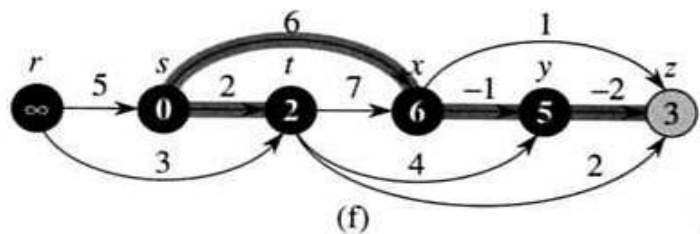
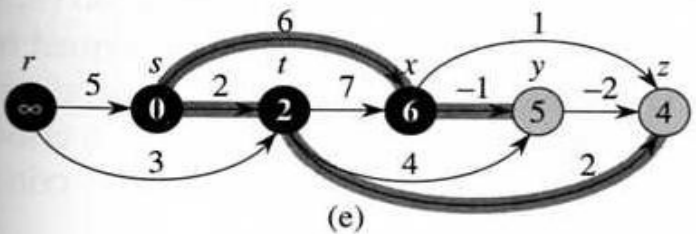
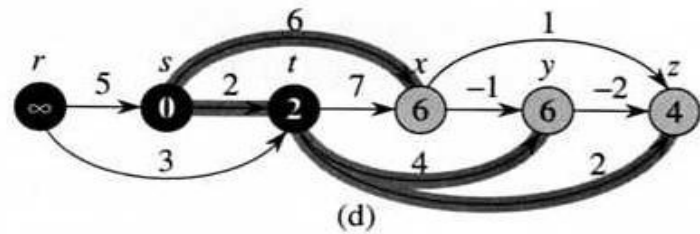
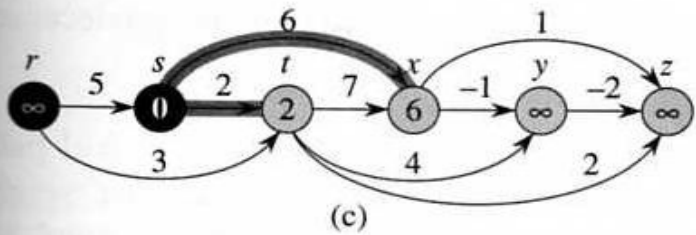
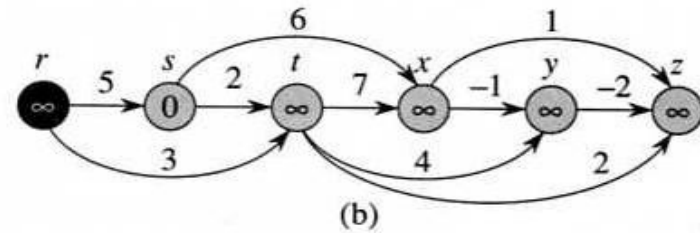
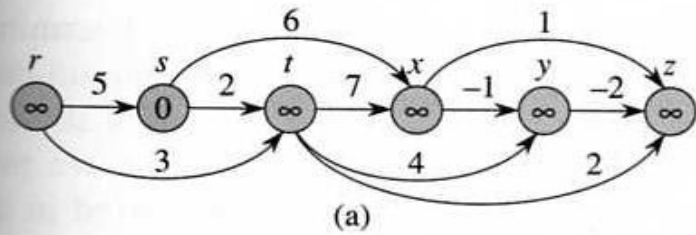
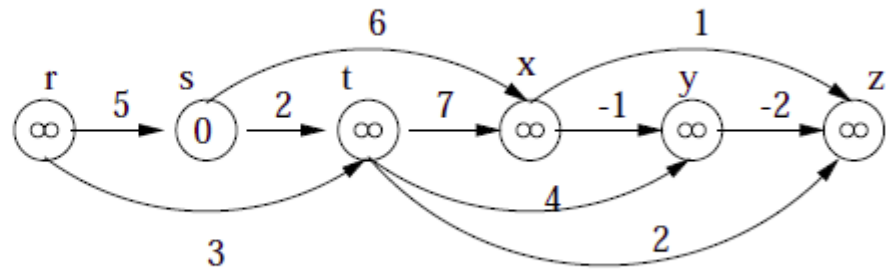
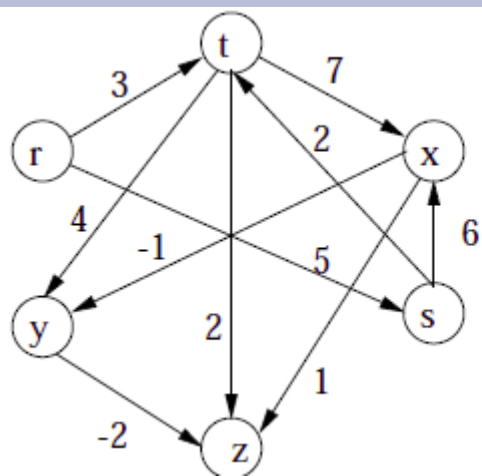
initialize graph from s

for each u in V in topological order

 for each v in $G.Adj[u]$

 Relax(u, v, w)

Runtime: $O(|V| + |E|)$



Directed Acyclic Graphs

Correctness:

Prove it!

Directed Acyclic Graphs

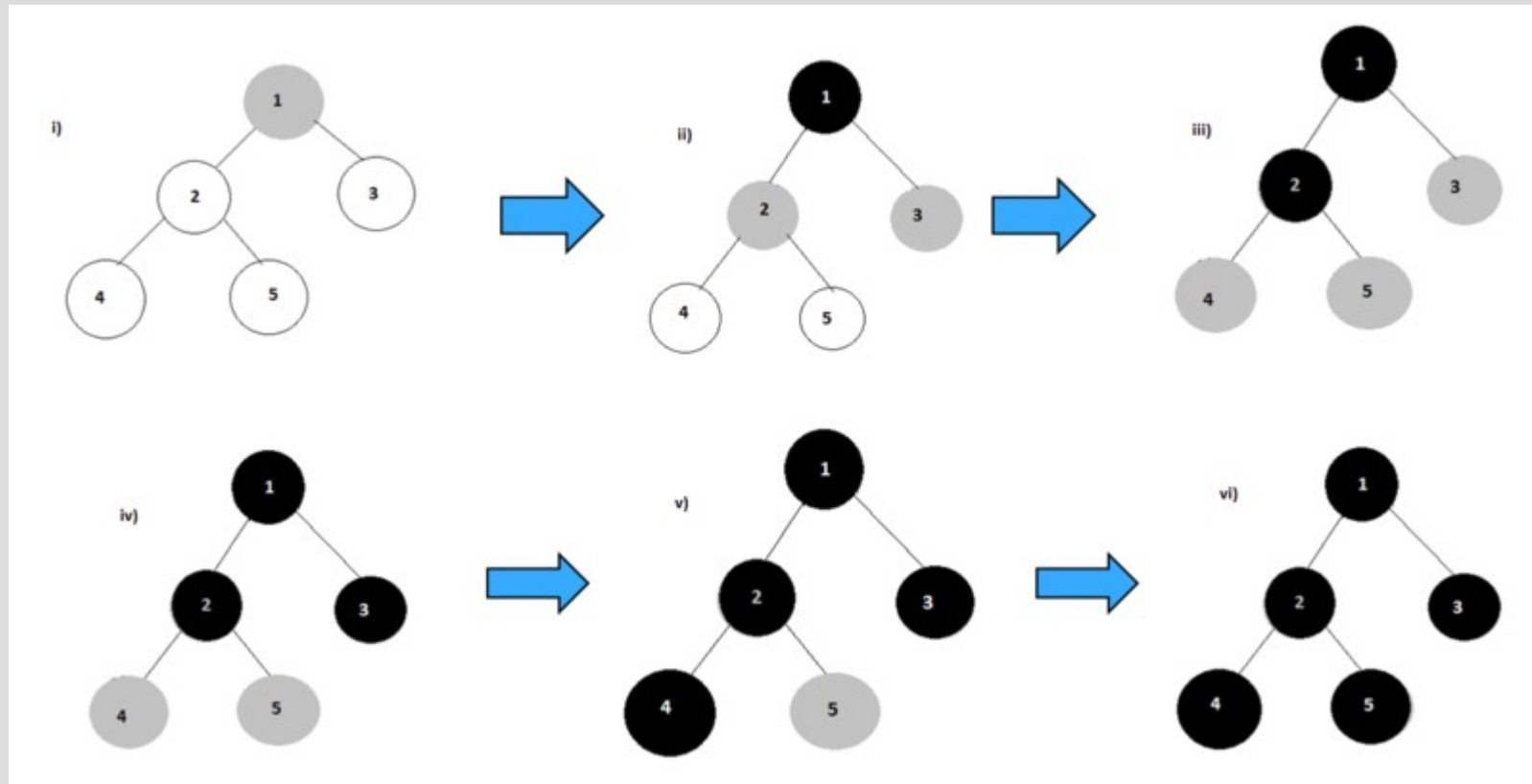
Correctness:

By definition of topological order,
When relaxing vertex v , we have
already relaxed any preceding
vertices

So by relaxation property 5, we have
found the shortest path to all v

BFS (unweighted graphs)

Create FIFO queue to explore unvisited nodes



Dijkstra

Dijkstra's algorithm is the BFS equivalent for non-negative weight graphs



Dijkstra

Dijkstra(G, w, s)

initialize G from s

$Q = G.V, S = \text{empty}$

while Q not empty

$u = \text{Extract-min}(Q)$

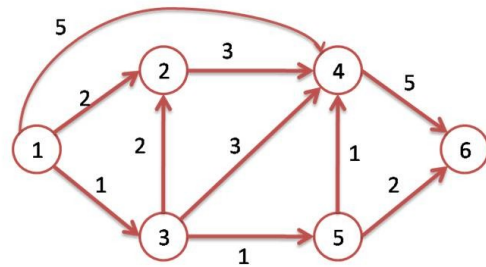
$S = S \cup \{u\}$

for each v in $G.\text{Adj}[u]$

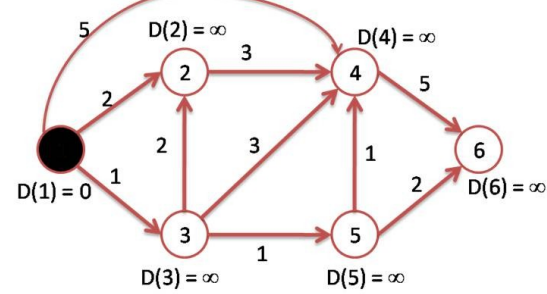
relax(u, v, w)

S optional

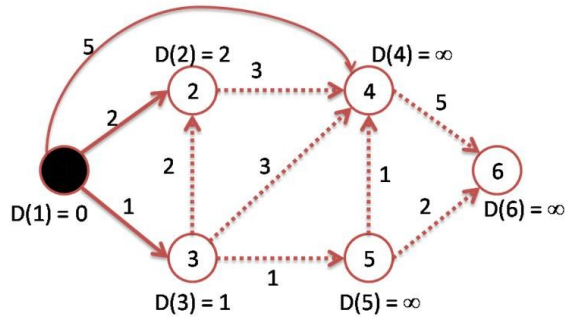




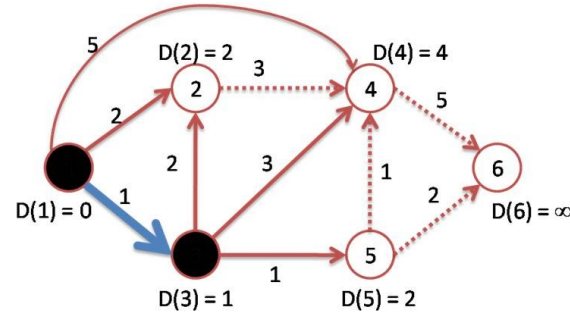
(a) Network Model



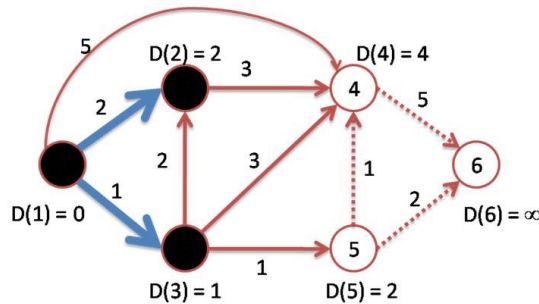
(b) Distance initialized



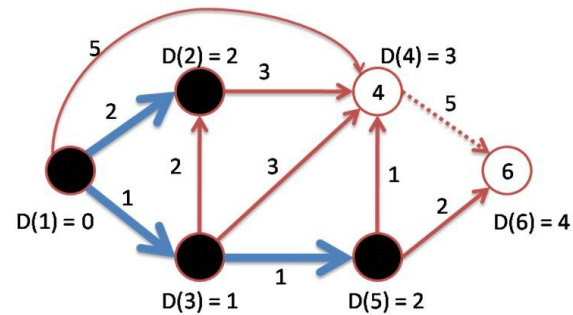
(c) Distance to adjacent nodes updated



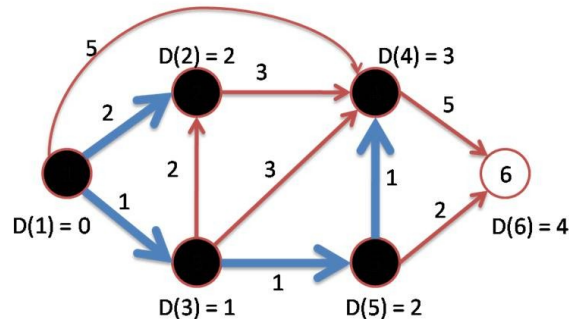
(d) Node 3 selected



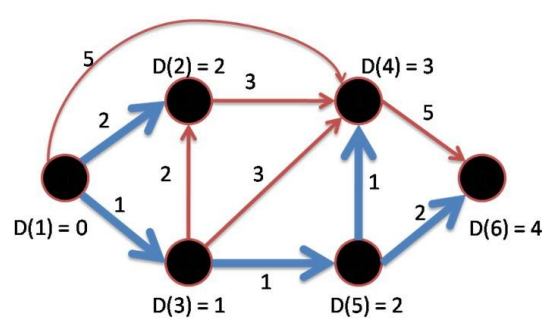
(e) Node 2 selected



(f) Node 5 selected



(g) Node 4 selected



(h) Shortest path found

Dijkstra

Runtime?

Dijkstra

Runtime:

Extract-min() run $|V|$ times

Relax runs Decrease-key() $|E|$ times

Both take $O(\lg n)$ time

So $O((|V| + |E|) \lg |V|)$ time

(can get to $O(|V| \lg |V| + E)$ using
Fibonacci heaps)

Dijkstra

Runtime note:

If G is almost fully connected,

$$|E| \approx |V|^2$$

Use a simple array to store v.d

$$\text{Extract-min}() = O(|V|)$$

$$\text{Decrease-key}() = O(1)$$

$$\text{total: } O(|V|^2 + E)$$

Dijkstra

Correctness: (p.660)

Sufficient to prove when u added to S , $u.d = \delta(s,u)$

Base: s added to S first, $s.d=0=\delta(s,s)$

Termination: Loop ends after Q is empty, so $V=S$ and we done

Dijkstra

Step: Assume v in S has $v.d = \delta(s,v)$

Let y be the first vertex outside S
on path of $\delta(s,u)$

We know by relaxation property 4,
that $\delta(s,y) = y.d$ (optimal sub-structure)

$y.d = \delta(s,y) \leq \delta(s,u) = u.d$, as $w(p) \geq 0$

Dijkstra

Step: Assume v in S has $v.d = \delta(s, v)$

But as u was picked before y ,

$u.d \leq y.d$, combined with $y.d \leq u.d$

$y.d = u.d$

Thus $y.d = \delta(s, y) = \delta(s, u) = u.d$