

# The Kernel (and Process) Abstraction

Chapter 2-3 OSPP

Part I

# Announcements

- Today: kernel
  - Asynchrony
  - Processes
  - Protection

# Kernel

- The software component that controls the hardware directly and implements the core privileged OS functions.
- Modern hardware has features that allow the OS kernel to protect itself from untrusted user code.

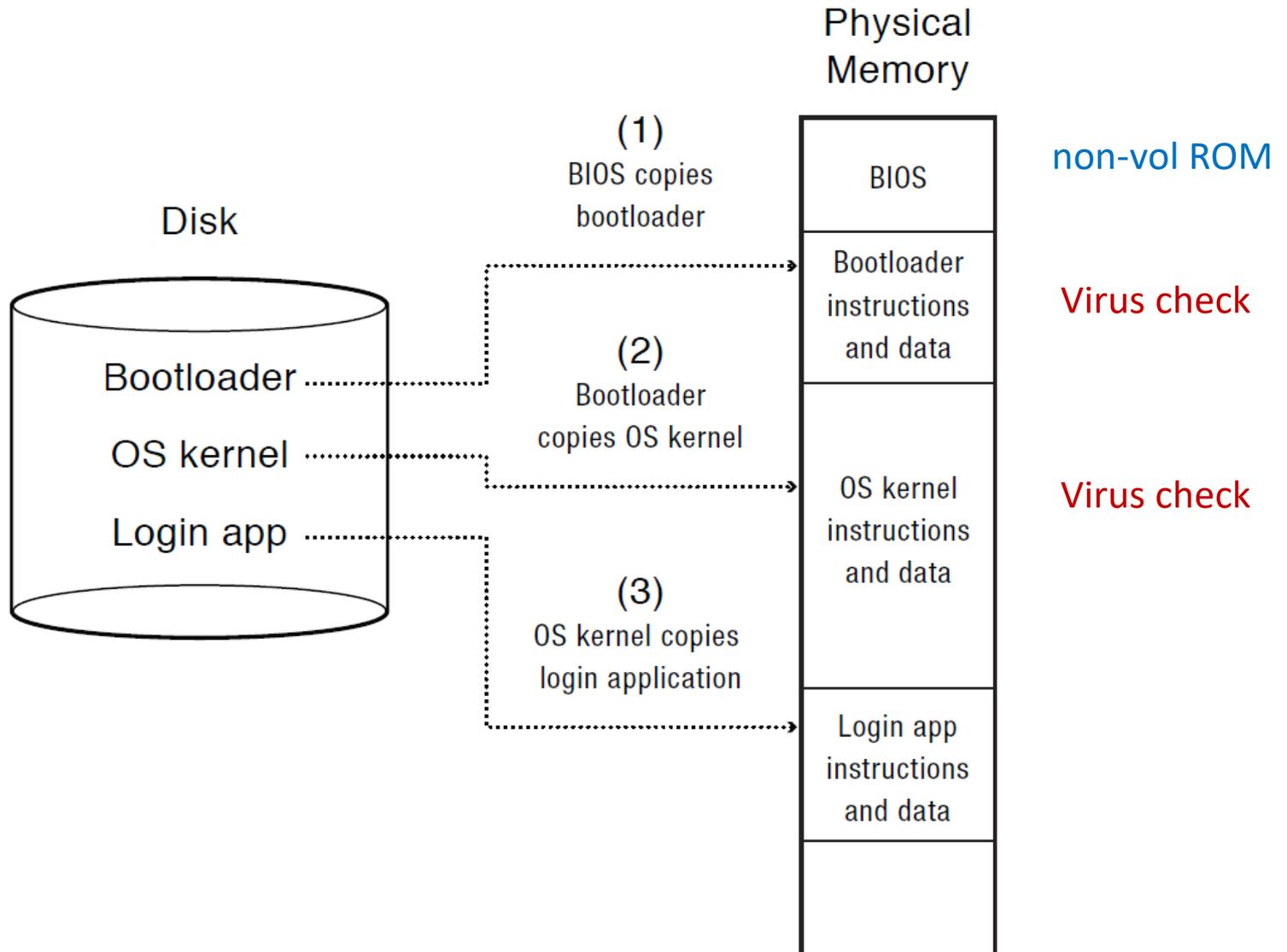
# Kernel Protection

- Reliability
  - crashes
- Security
  - Write to arbitrary disk (or memory) locations
- Privacy
  - User files

# Does kernel/OS teach any lessons I can use?

- Yes!
- Protection
  - Trend is for apps to be mini-OS?
  - Browser
- Resource management
  - Trend is to give apps X resources and let them figure out how to share
  - User threads, virtual machines
- Asynchrony and many others

# A Short Digression: Starting the Kernel: Booting



# Challenge: Asynchrony: Device Interrupts

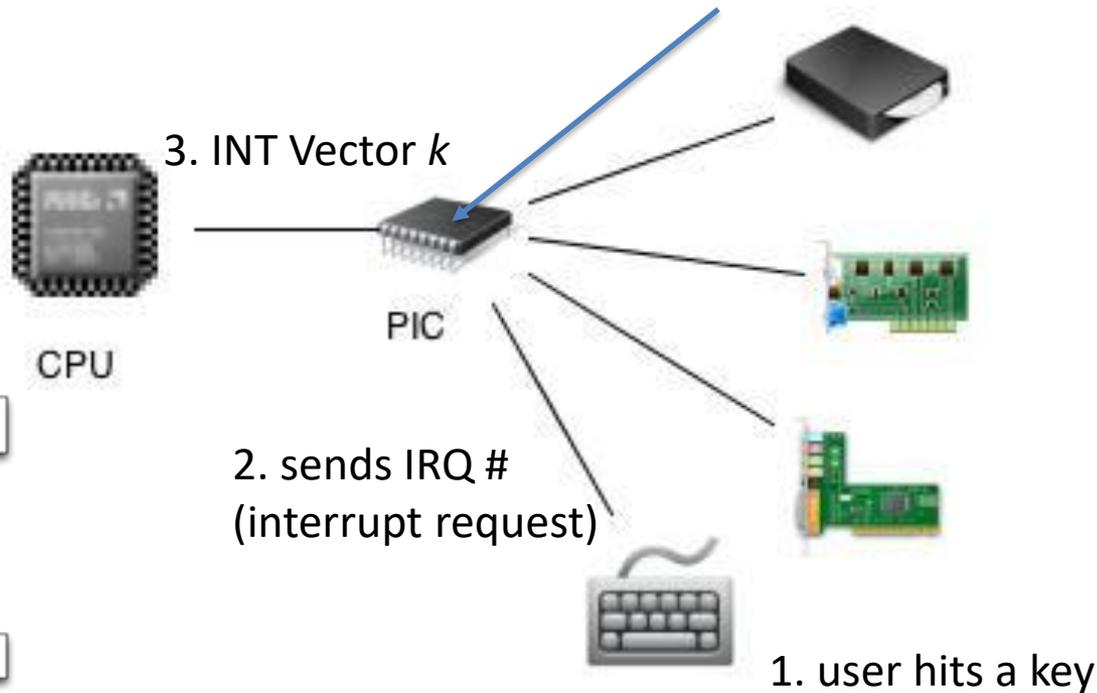
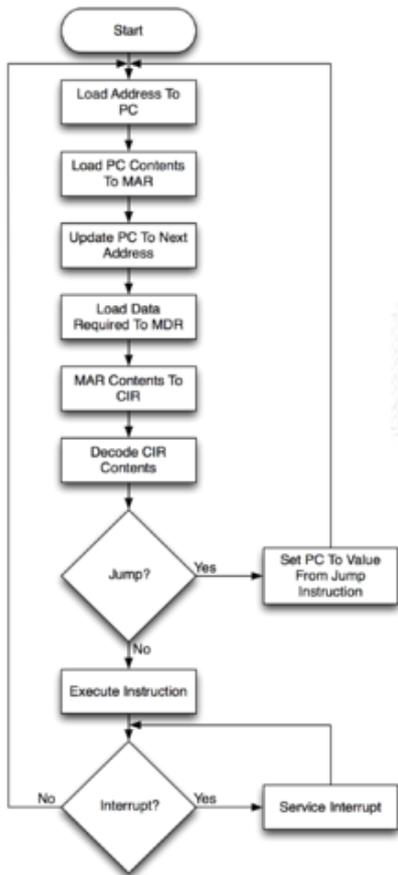
- OS kernel needs to communicate with physical devices
- Devices operate asynchronously from the CPU
  - Polling: Kernel waits until I/O is done
  - Interrupts: Kernel can do other work in the meantime
- Device access to memory
  - Programmed I/O: CPU reads and writes to device
  - Direct memory access (DMA) by device

# Device Interrupts

- How do device interrupts work?
  - Where does the CPU run after an interrupt?
  - What is the interrupt handler written in? C? Java?
  - What stack does it use?
  - Is the work the CPU had been doing before the interrupt lost forever?
  - If not, how does the CPU know how to resume that work?
  - Will come back to this soon

# How it all happens

programmable interrupt controller (x86)



CPU checks for interrupts after each instruction cycle  
oops, looks like we are “polling” after all but in h/w 😊

# Device Driver and I/O Interrupts

- Top half of driver called from syscall handler
  - issues privileged instructions: read from disk, done
- Bottom half
  - called when interrupt arrives
  - interrupt handling: I/O completion or error recovery

# Interrupt Handler

- Bottom half
  - runs first called directly by hardware, saves state of hardware, then enables top half to run
- Top half ~ interrupt handler specifics
  - for an I/O event: calls driver bottom half: e.g. data copying

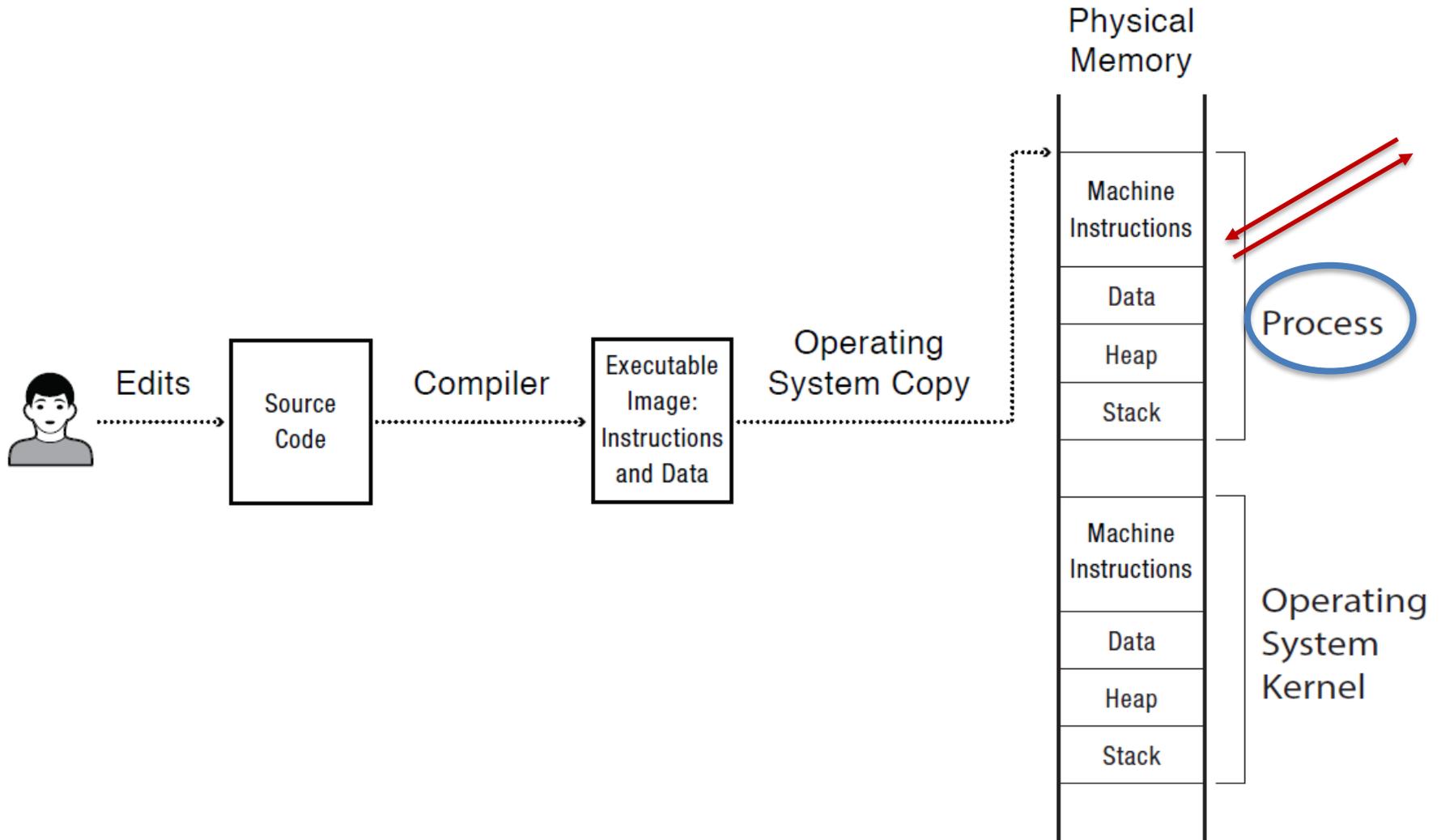
# Buggy Device Drivers

- Validate/inspect
- User-level drivers
- Running drivers in VM
- Sandboxing
  - mini-execution environment in the kernel

# Challenge: Protection

- How do we execute code with restricted privileges?
  - Either because the code is buggy or if it might be malicious
- Some examples:
  - A script running in a web browser
  - A program you just downloaded off the Internet
  - A program you just wrote that you haven't tested yet
  - First see how OS does it

# A Problem: both constrain and protect process



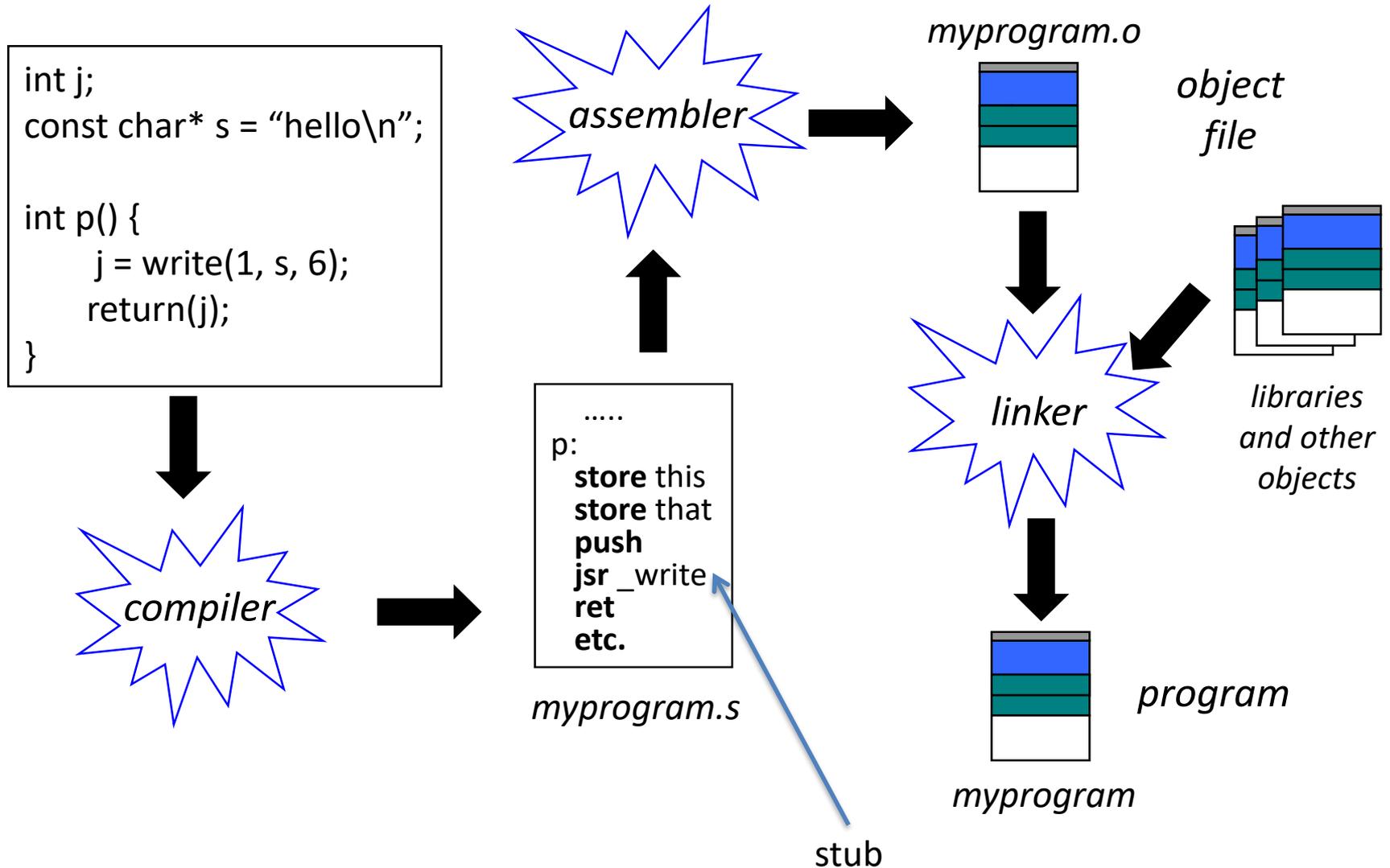
# Main Points

- Process concept
  - A process is the OS abstraction for executing a program with **limited** privileges but that is **isolated**
- Dual-mode operation: user vs. kernel
  - Kernel-mode: execute with complete privileges
  - User-mode: execute with fewer privileges
  - Processor is a warden (OS) and an inmate (process)!
- Safe control transfer
  - How do we switch from one mode to the other?

# Process Abstraction

- Process: an *instance* of a program, running with limited rights
  - Thread: a sequence of instructions within a process
    - Potentially many threads per process (for now 1:1)
  - Address space: set of rights of a process
    - Memory that the process can access
  - Other permissions the process has (e.g., which system calls it can make, what files it can access)

# The Birth of a Program



# Birth of a Process: Process State

Stored in **PCB** (Process Control Block)

Information associated with each process

- Program counter, stack pointer
- CPU registers
- CPU scheduling information
- Memory-management information
- Accounting information
- I/O status information
- Open files, signals (if UNIX)

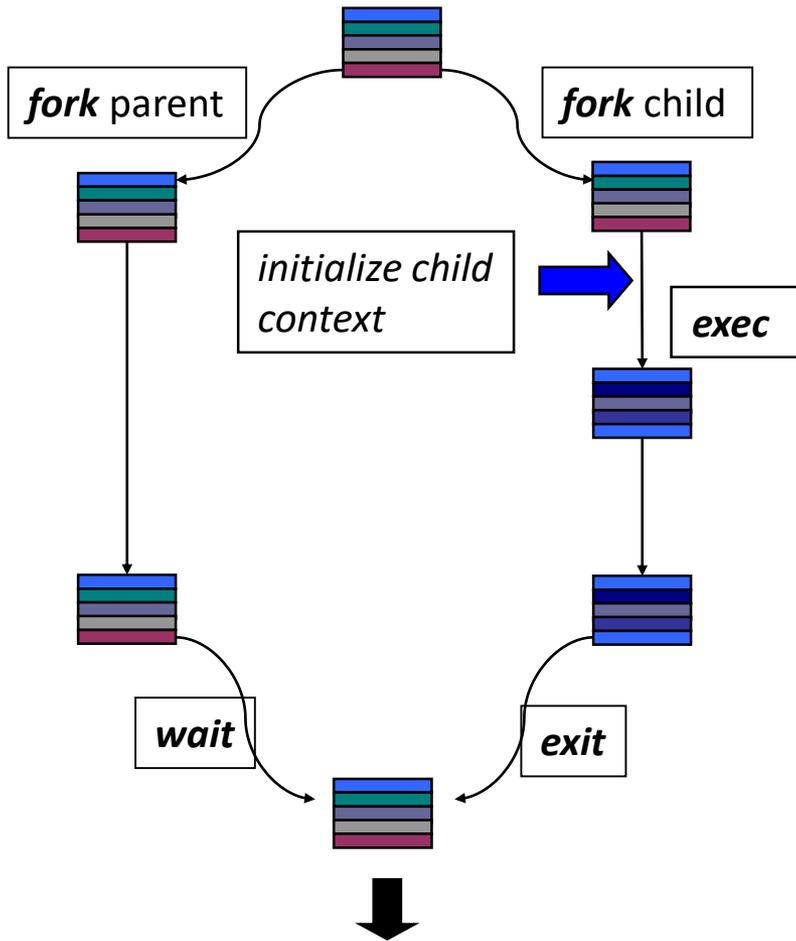
# Process API

- Very briefly

# UNIX Process Management

- UNIX fork – system call to create a copy of the current process, and start it running
  - No arguments!
- UNIX exec – system call to change the program being run by the current process
- UNIX wait – system call to wait for a process to finish
- UNIX signal – system call to send a notification to another process
- UNIX/LINUX clone – similar to fork but used with threads

# Unix Fork/Exec/Exit/Wait Example



```
int pid = fork();  
    Create a new process that is a clone of  
    its parent.  
  
exec*("program" [, argv, envp]);  
    Overlay the calling process virtual  
    memory with a new program, and  
    transfer control to it.  
  
exit(status);  
    Exit with status, destroying the process.  
  
int pid = wait*(&status);  
    Wait for exit (or other status change) of  
    a child.
```

Corner cases: orphans and zombies

# Example: Process Creation in Unix

```
int pid;  
int status = 0;  
  
if (pid = fork()) {  
    /* parent */  
    ....  
    pid = wait(&status);  
} else {  
    /* child */  
    ....  
    exit(status);  
}
```

The **fork** syscall returns twice: it returns a zero to the child and the child process ID (pid) to the parent.

Parent uses **wait** to sleep until the child exits; **wait** returns child pid and status.

# Implementing UNIX fork

## Steps to implement UNIX fork

- Create and initialize the process control block (PCB) in the kernel
- Create a new address space
- Initialize the address space with a copy of the entire contents of the address space of the parent
  - mostly sets up the page table
  - some implementations share portions of address space initially (copy-on-write)
- Inherit parent execution context (e.g., any open files, PC, SP)
- Inform the scheduler that the new process is ready to run

# Implementing UNIX exec

- Steps to implement UNIX exec
  - Load the program into the current address space
  - Copy arguments into memory in the address space
  - Initialize the hardware context to start execution at ``start'' (reset PC)

# Questions

- Can UNIX `fork()` return an error? Why?
- Can UNIX `exec()` return an error? Why?
- Can UNIX `wait()` ever return immediately? Why?

# Starting a New Process

- Allocate PCB; in Unix this is already done by `fork`
- Allocate memory (as needed, on demand)
  - “Copy” program from disk into memory
  - Allocate user stack
  - Allocate heap
- Allocate kernel stack (sys calls, interrupts, exceptions)

# Starting a New Process (cont'd)

- Transfer to user mode
- If Exec path (vs. fork)
  - Copy arguments into user memory (e.g. `argc`, `argv`)
  - Jump to `start` address

```
start (arg1, arg2) {  
    main (arg1, arg2);  
    exit ();  
}
```

Why not just call main?

# Back to Protection

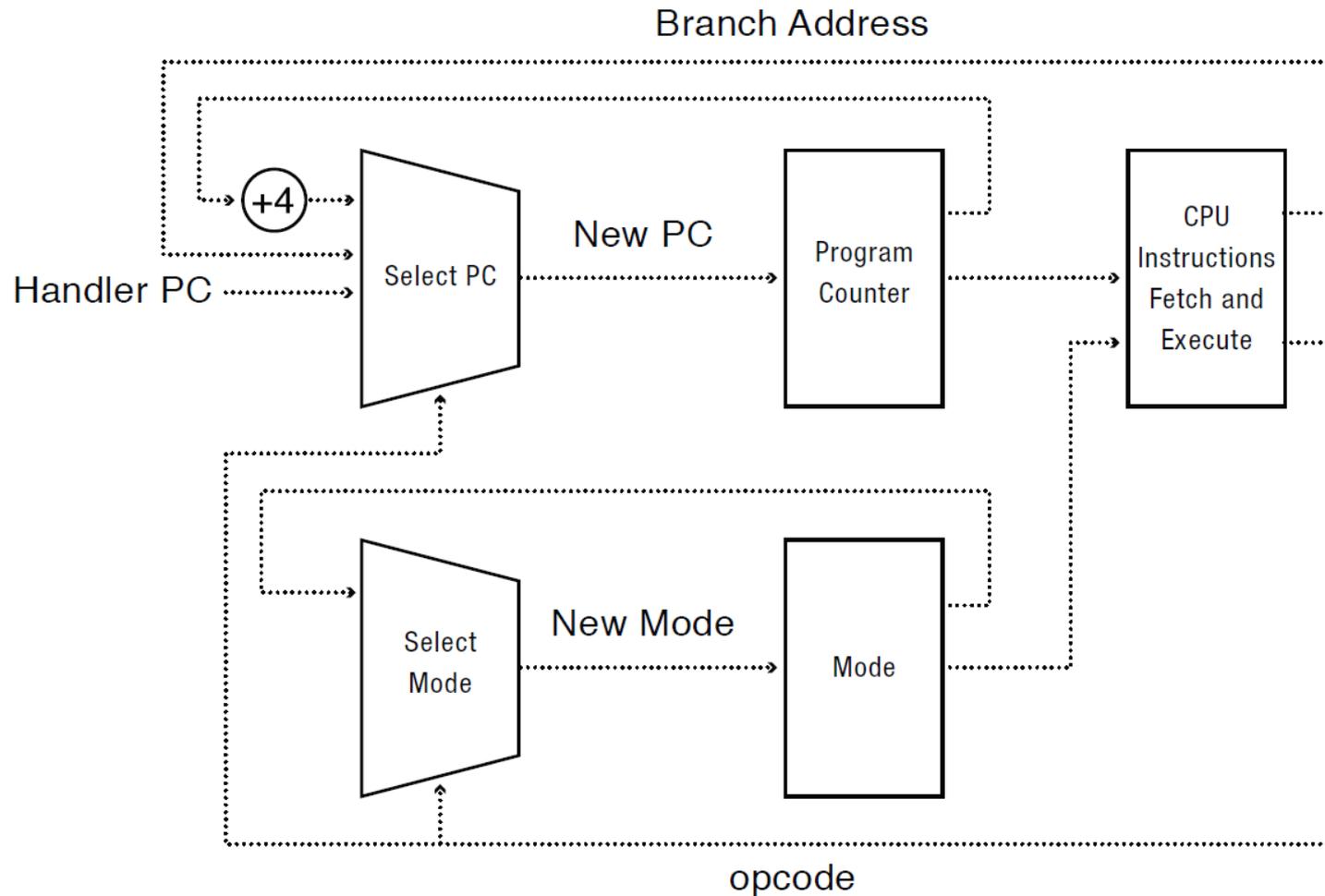
# Thought Experiment

- How can we implement execution with limited privilege (no hardware support)?
- How do we go faster?

# Hardware Support: Dual-Mode Operation

- Kernel mode
  - Execution with the full privileges of the hardware
  - Read/write to any memory, access any I/O device, read/write any disk sector, send/read any packet
- User mode
  - Limited privileges
  - Only those granted by the operating system kernel
- On the x86, mode stored in EFLAGS register
- On the MIPS, mode in the status register

# A CPU with Dual-Mode Operation



Where do interrupts fit in?

# The Kernel Abstraction

Chapter 2 OSPP

Part II

# Hardware Support: Dual-Mode Operation

- Privileged instructions
  - Available to kernel
  - Not available to user code
- Limits on memory accesses
  - To prevent user code from overwriting the kernel
- Timer
  - To regain control from a user program in a loop
- Safe way to switch from user mode to kernel mode, and vice versa

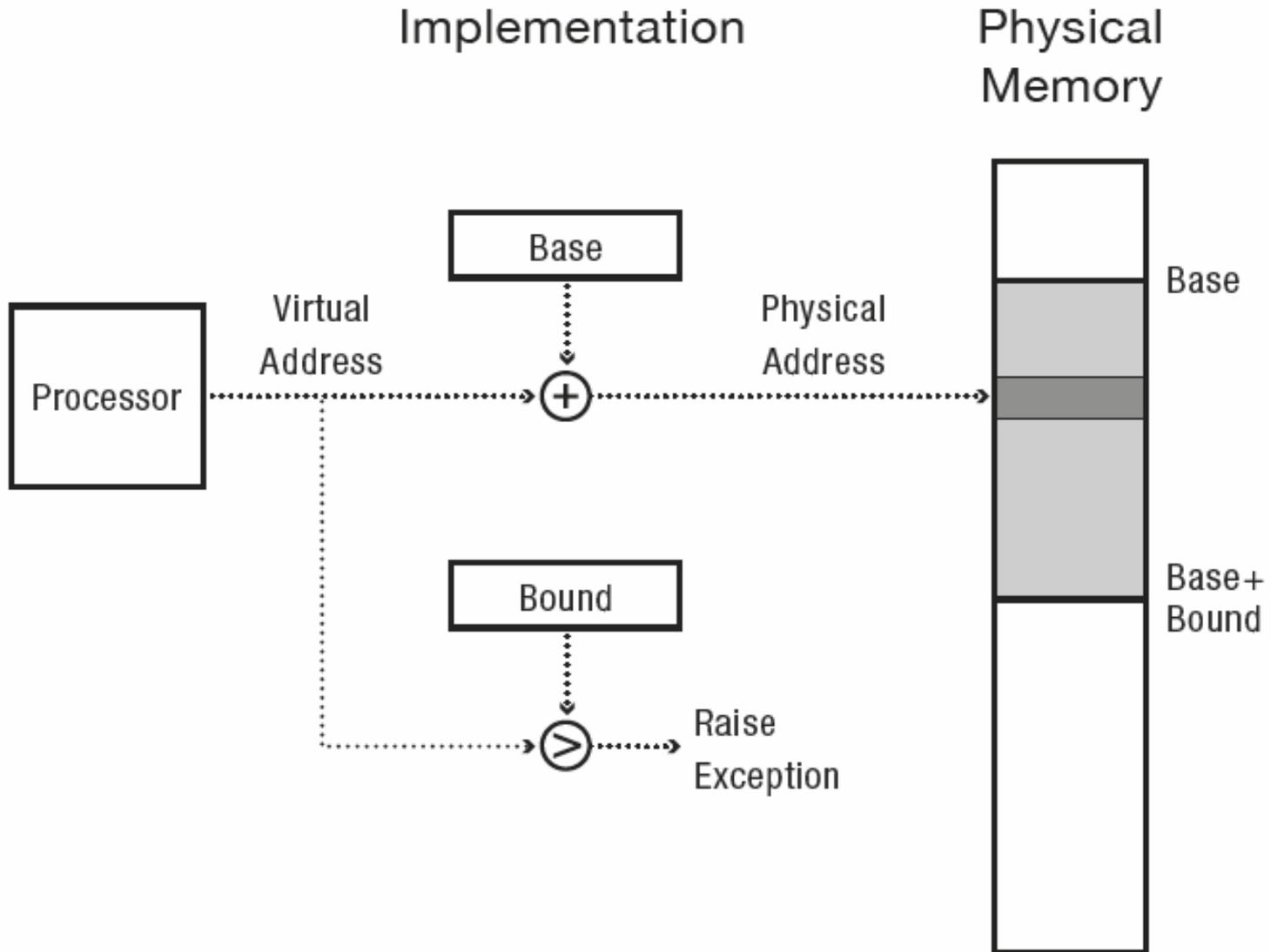
# Privileged instructions

- Examples?
- What should happen if a user program attempts to execute a privileged instruction?

# Question

- For a “Hello world” program, the kernel must copy the string from the user program memory into the screen memory.
- Why not allow the application to write directly to the screen’s buffer memory?

# Simple Memory Protection

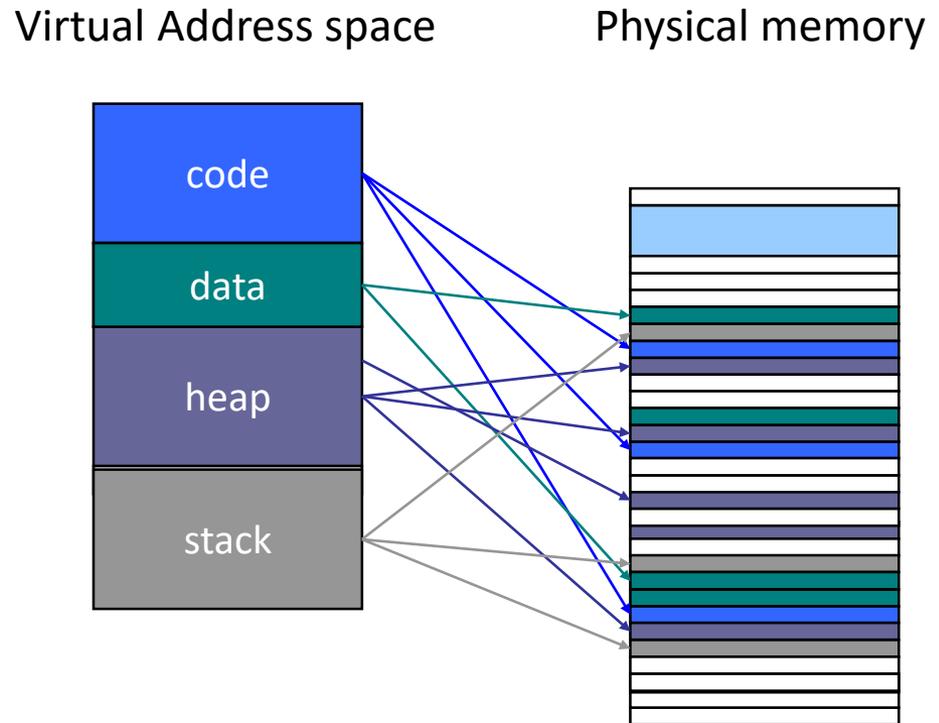


# Towards Virtual Addresses

- Problems with base and bound?

# Virtual Addresses

- Translation done in hardware, using a table
- Table set up by operating system kernel



# Example

```
int staticVar = 0;           // a static variable
main() {
    int local_var;
    staticVar += 1;
    sleep(10); // sleep for x seconds
    printf ("static address: %p, local: %p\n",
            &staticVar, &localVar);
}
```

**What happens if we run two instances of this program at the same time: `staticVar`, `localVar`?**

# Back to Interrupts: Hardware Timer

- Hardware device that periodically interrupts the processor
  - Returns control to the kernel handler
  - Interrupt frequency set by the kernel
    - Not by user code!
  - Interrupts can be temporarily deferred
    - Not by user code!
    - Interrupt deferral crucial for implementing mutual exclusion
  - Important for protection as well as scheduling

# Mode Switch

- From user mode to kernel mode
  - Interrupts
    - Triggered by timer and I/O devices
  - Exceptions
    - Triggered by unexpected program behavior
    - Or malicious behavior!
  - System calls (aka protected procedure call)
    - Request by program for kernel to do some operation on its behalf
    - Only limited # of very carefully coded entry points

# Simple Examples

- Examples of exceptions
  - Memory error
  - Divide by 0
- Examples of system calls
  - `read/write`

# Mode Switch

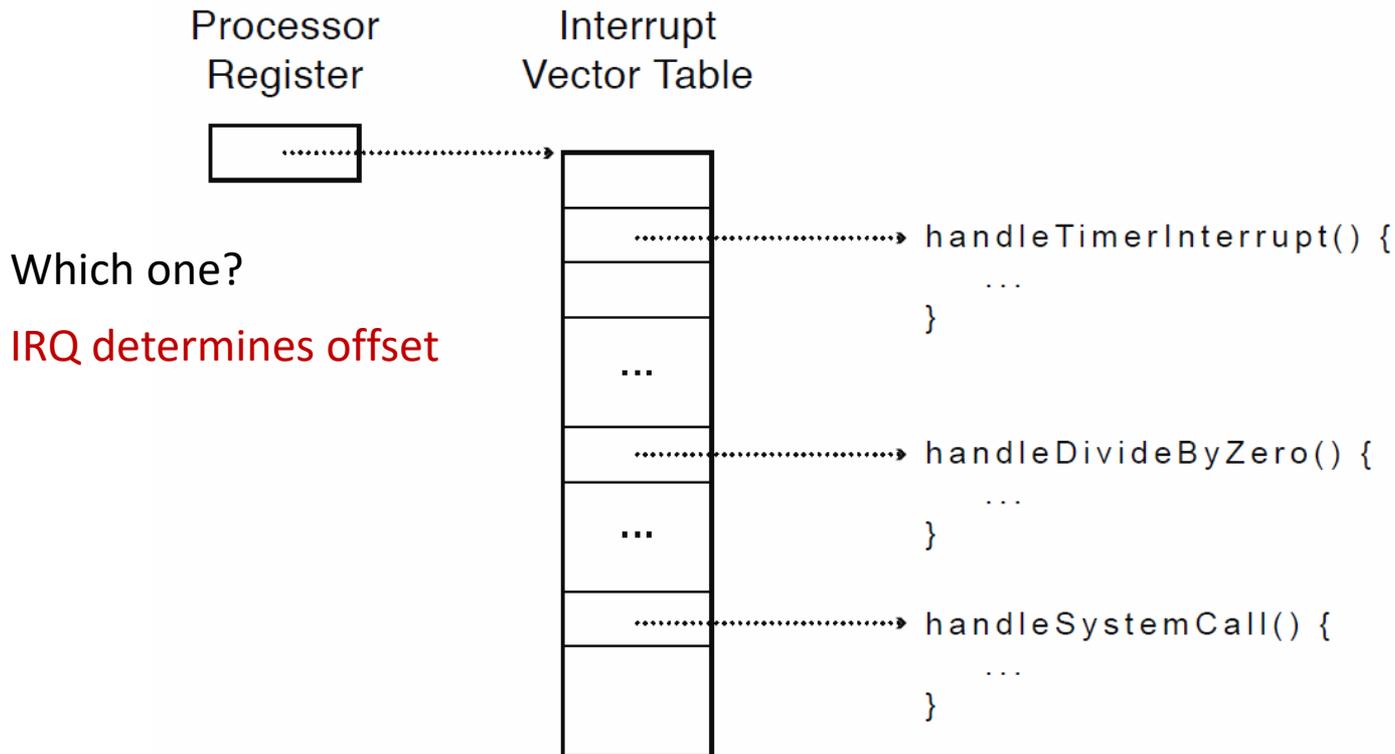
- From kernel mode to user mode
  - New process/new thread start
    - Jump to first instruction in program/thread
  - Return from interrupt, exception, system call
    - Resume suspended execution
  - Process/thread context switch
    - Resume some other process
  - User-level upcall (UNIX signal)
    - Asynchronous notification to user program

# How do we handle interrupts safely?

- Interrupt vector
  - Limited number of entry points into kernel
- Atomic transfer of control
  - Single instruction to change (all changed together)
    - Program counter
    - Stack pointer
    - Kernel/user mode
    - Memory protection
- Transparent re-startable execution
  - User program does not know interrupt occurred

# Interrupt Vector

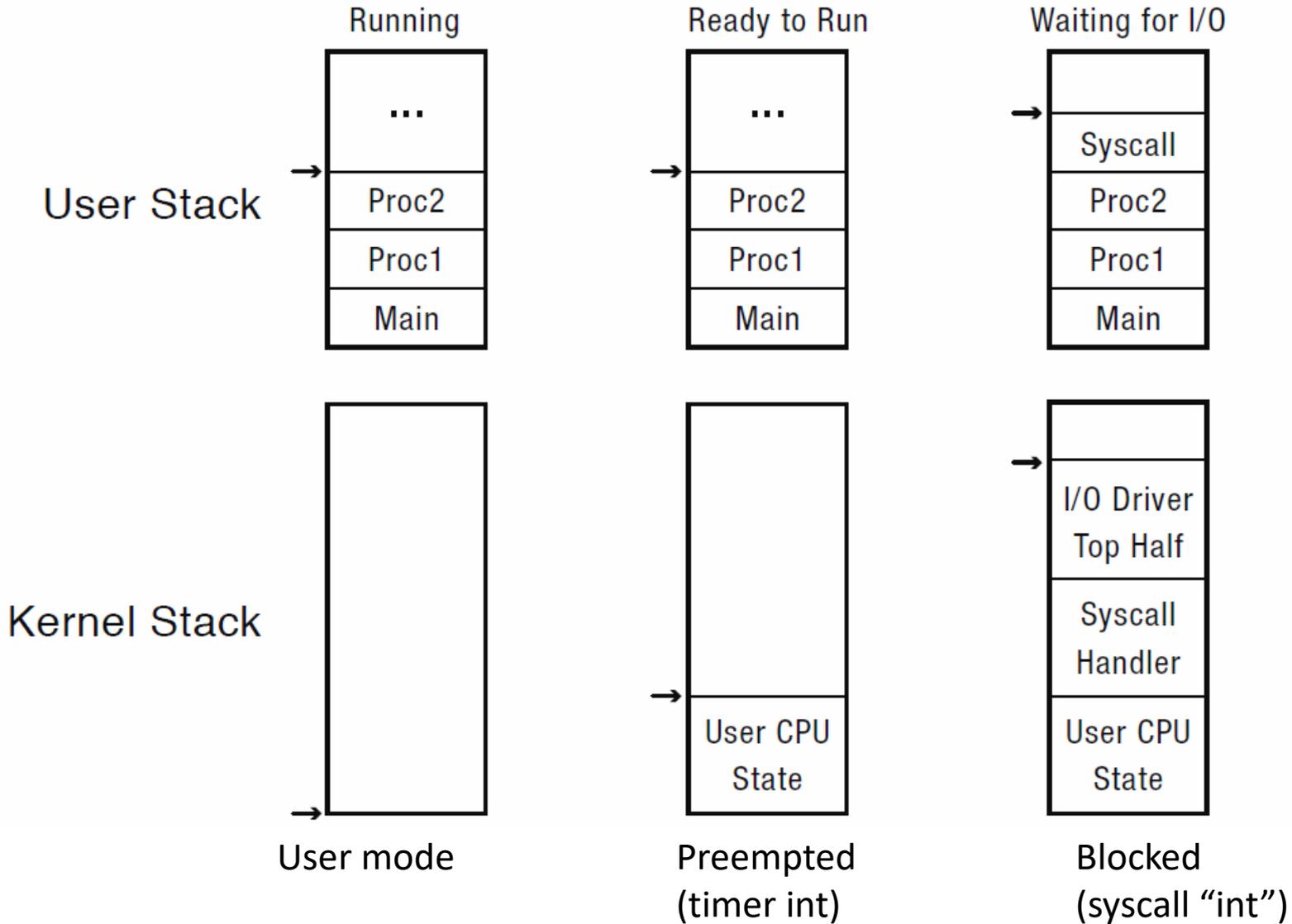
- Table set up by OS kernel; pointers to code to run on different events



# Interrupt Stack

- Per-processor, located in kernel (not user) memory
  - Usually a process/thread has both: kernel and user stack
- Why can't the interrupt handler run on the stack of the interrupted user process?
  - user stack may be corrupted or modified

# Interrupt Stack



# Interrupt Masking

- Interrupt handler runs with interrupts off
  - Why do we need to mask/buffer interrupts in the handler?
  - Re-enabled when interrupt completes
- OS kernel can also turn interrupts off
  - Eg., when determining the next process/thread to run
  - On x86
    - CLI: disable interrupts
    - STI: enable interrupts
    - Only applies to the current CPU core
- We'll need this to implement synchronization in chapter 5

# Case Study: x86 Interrupt

- Save current stack pointer
- Save current program counter
- Save current processor status word (condition codes: conditional results, arithmetic carry, ...)
- Switch to kernel stack; put SP, PC, PSW on stack
- **Switch to kernel mode**
- Vector through interrupt table
- Interrupt handler saves registers it might use
  - `pushad`: save 'em all

# Before Interrupt

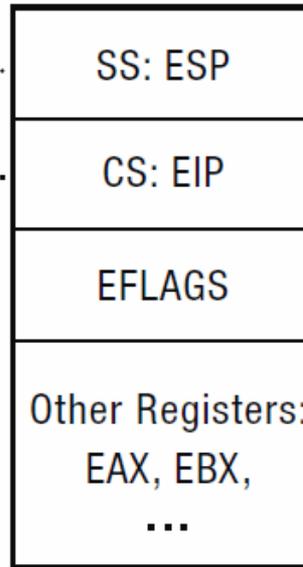
User-level Process

```
foo () {  
  while(...) {  
    x = x+1;  
    y = y-2;  
  }  
}
```

User Stack



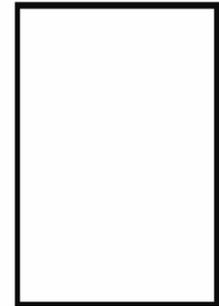
Registers



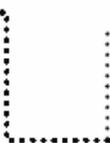
Kernel

```
handler() {  
  pushad  
  ...  
}
```

Interrupt Stack



← PSW

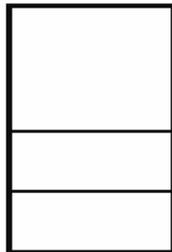


# Jumped to Interrupt Handler

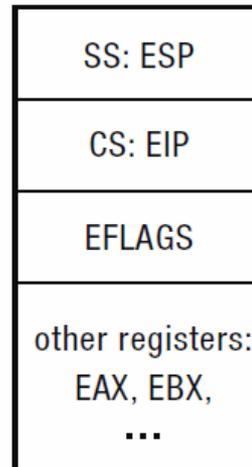
User-level Process

```
foo () {  
  while(...) {  
    x = x+1;  
    y = y-2;  
  }  
}
```

User Stack



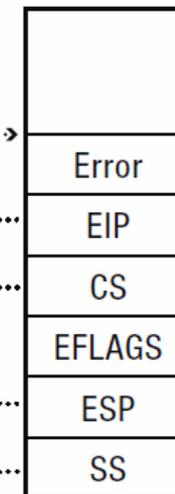
Registers



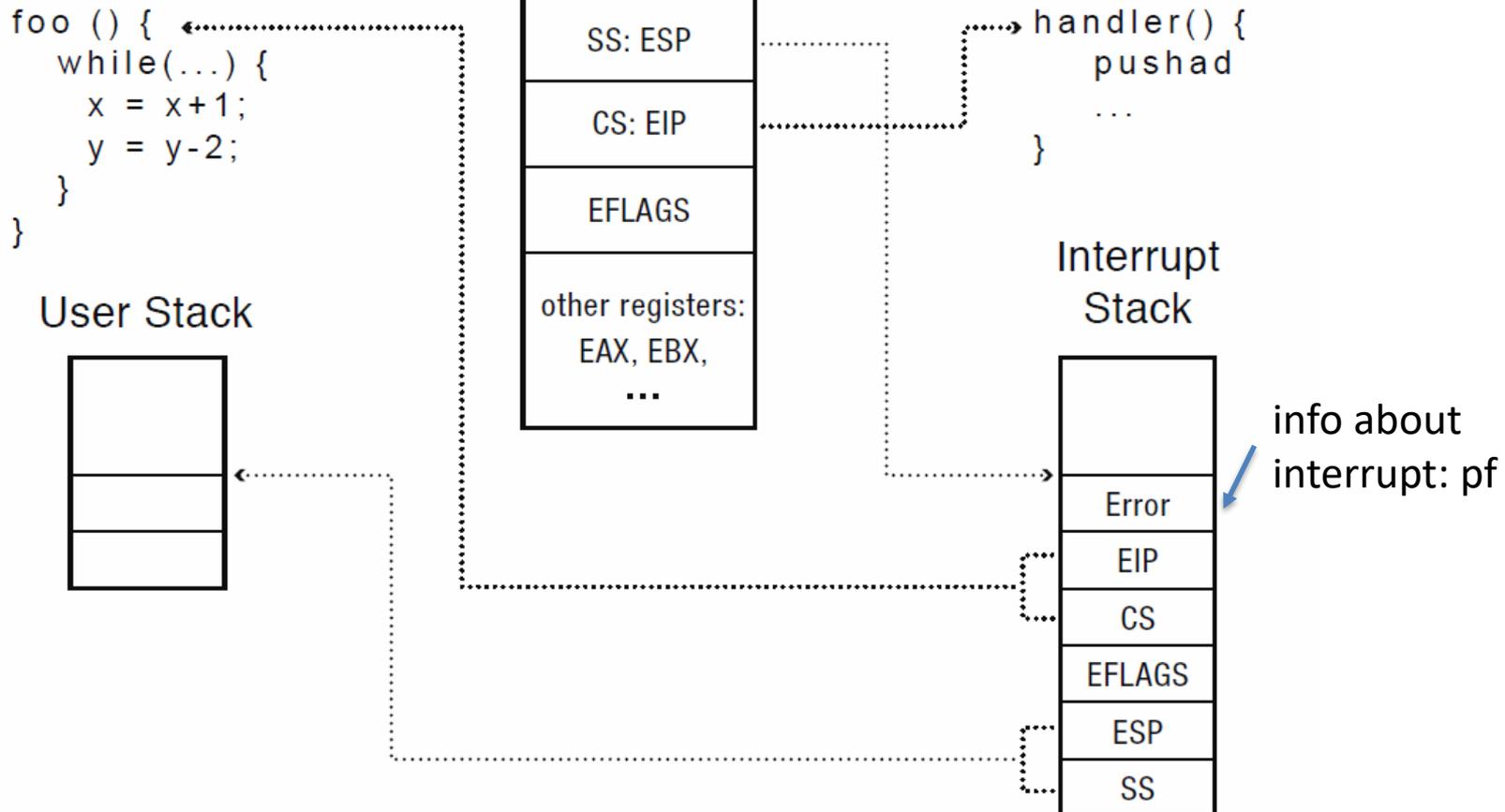
Kernel

```
handler() {  
  pushad  
  ...  
}
```

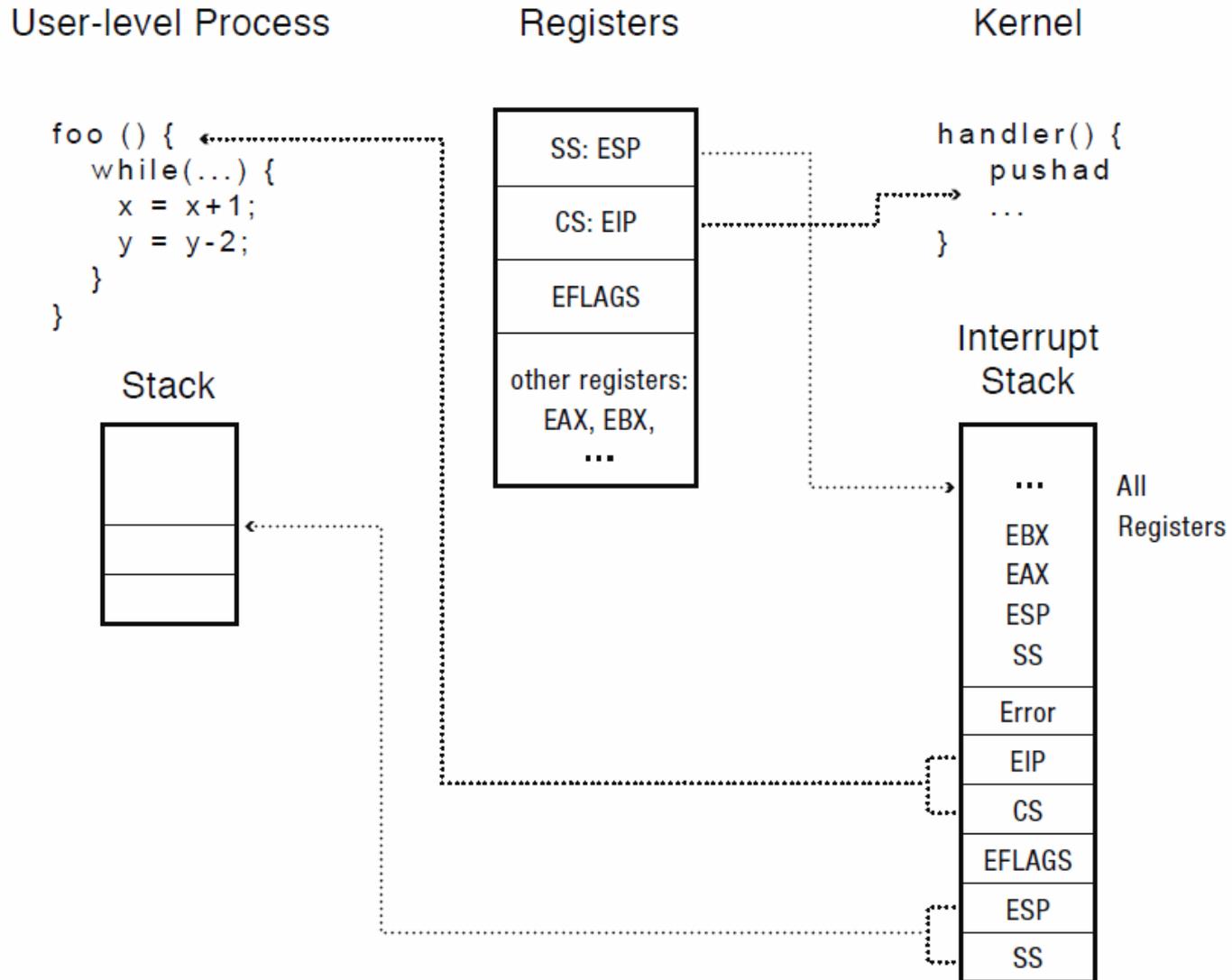
Interrupt Stack



info about interrupt: pf



# Executing the handler



# At end of handler

- Handler restores saved registers
- Atomically returns to interrupted process/thread (hopefully)
  - Restore program counter
  - Restore program stack
  - Restore processor status word
  - **Switch to user mode**

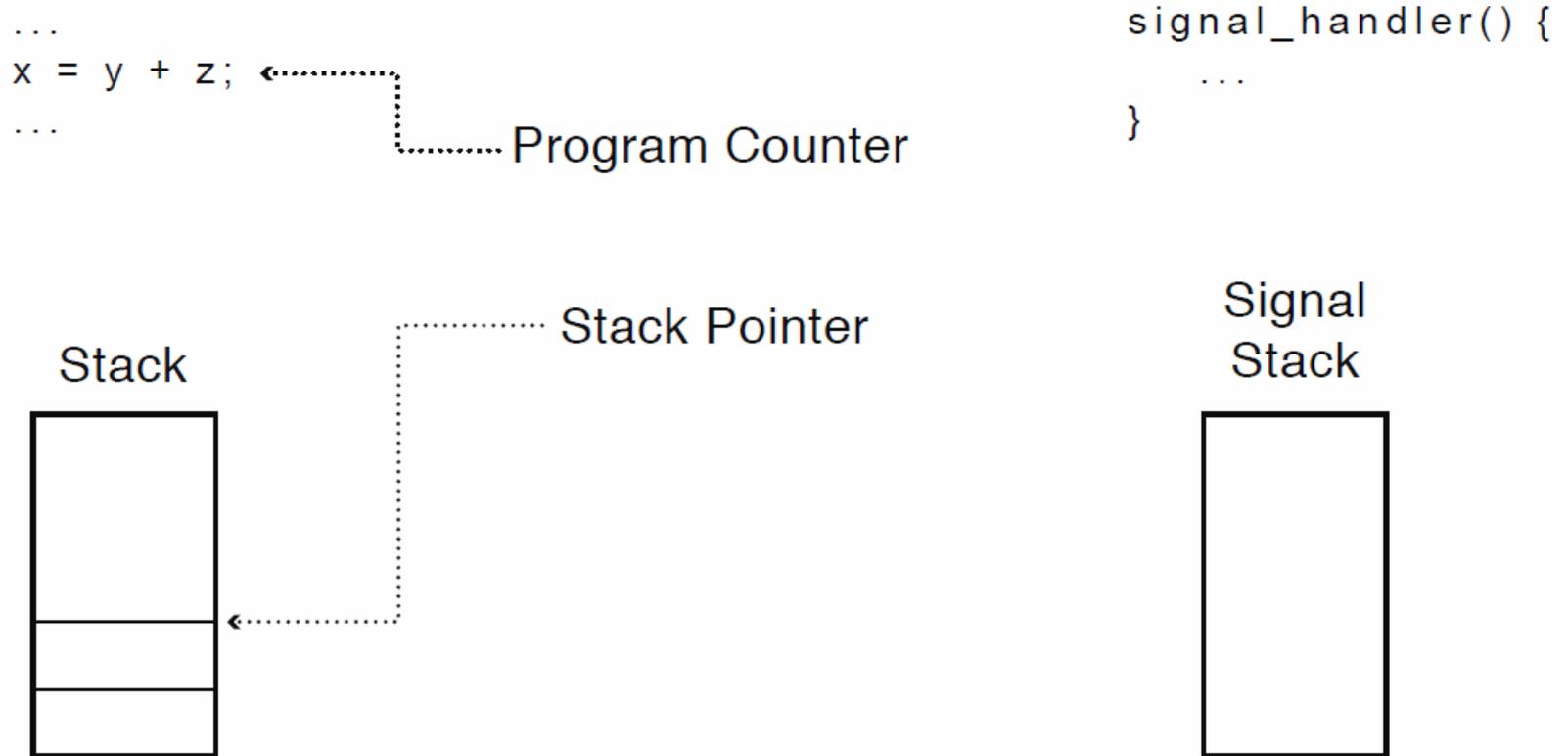
# Upcall: User-level event delivery

- Notify user process of some event that needs to be handled right away
  - Time expiration
    - Real-time alarm
    - Time-slice for user-level thread manager
  - Interrupt delivery for VM player
  - Asynchronous I/O completion (`async/await`)
- AKA UNIX signal

# Upcalls vs Interrupts

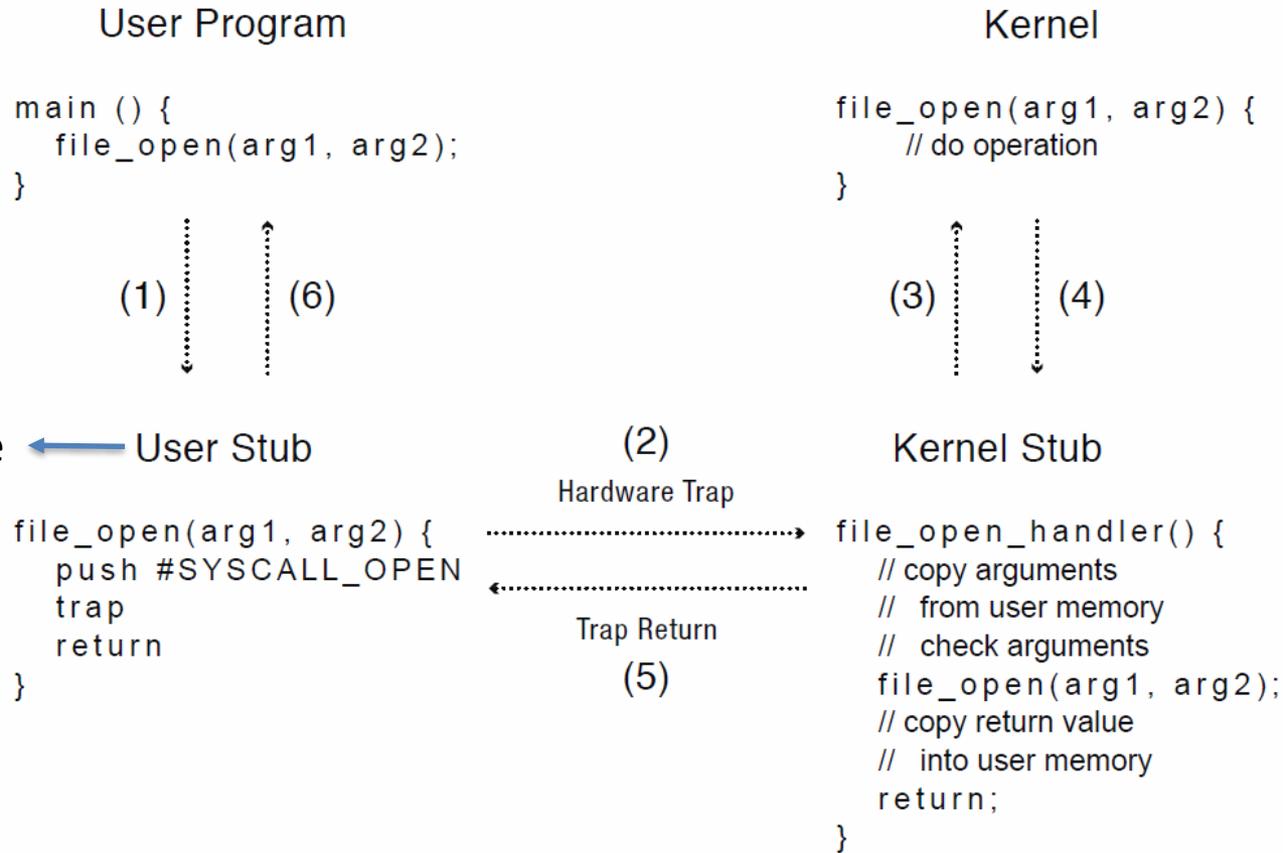
- Signal handlers ~ interrupt vector
- Signal stack ~ interrupt stack
- Automatic save/restore registers = transparent resume
- Signal masking: signals disabled while in signal handler
- But it runs in user-land

# Upcall: Before





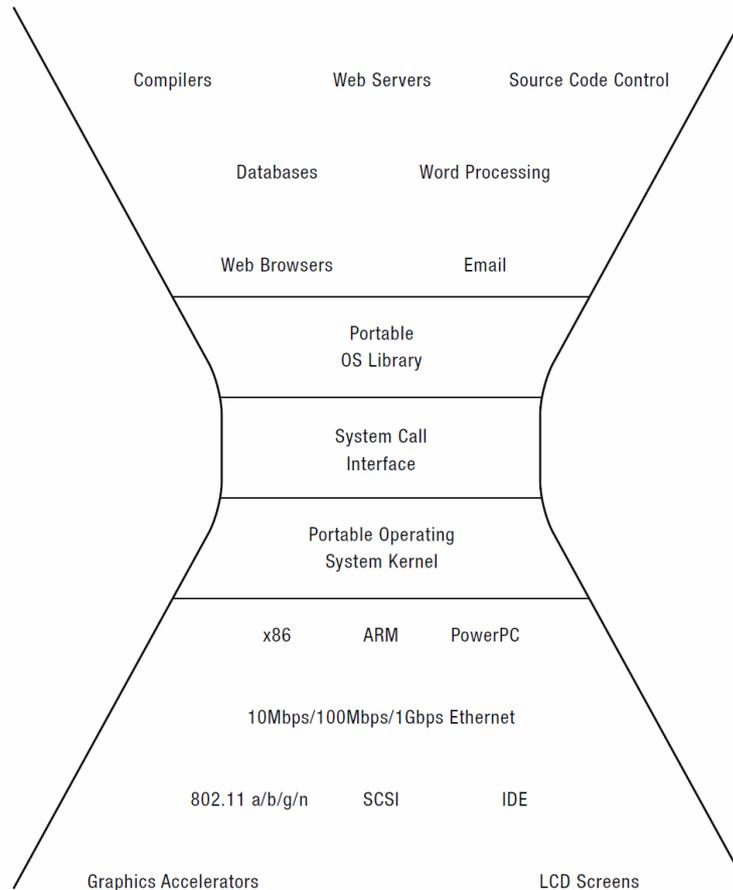
# Making system calls secure



# Kernel System Call Handler

- Locate arguments
  - In registers or on user stack
  - *Translate* user addresses (VA) into kernel addresses (PA)
- Copy arguments
  - From user memory into kernel memory
  - Protect kernel from malicious code evading checks
  - **Time-of-check vs. Time-of-use (TOCTOU) attack avoided**
- Validate arguments
  - Protect kernel from errors in user code
- Copy results back into user memory
  - *Translate* kernel addresses into user addresses

# Genius of OS software stack



# One Implication of this

- Get to choose where to put functionality
- User-level process
  - Unix: user-level shell, login
- User-level library
  - Unix: lib.c (I/O, fork/exec, ...)
- OS kernel
  - File system, network stack, etc

# Next Week

- Threads
- Read Chap. 4 OSPP