Convergence theory

- Background: Best uniform approximation;
- Chebyshev polynomials;
- Analysis of the CG algorithm;
- Analysis in the non-Hermitian case (short)

Background: Best uniform approximation

We seek a function ϕ (e.g. polynomial) which deviates as little as possible from f in the sense of the $\|\cdot\|_{\infty}$ -norm, i.e., we seek the

$$\min_{\phi} \max_{t \in [a,b]} |f(t) - \phi(t)| = \min_{\phi} \|f - \phi\|_{\infty}$$

where ϕ is in a finite dimensional space (e.g., space of polynomials of degree $\leq n$)

- ightharpoonup Solution is the "best uniform approximation to f"
- \blacktriangleright Important case: ϕ is a polynomial of degree $\leq n$
- \blacktriangleright In this case ϕ belongs to \mathbb{P}_n

The Min-Max Problem:

$$ho_n(f) = \min_{p \in \mathbb{P}_n} \;\; \max_{x \in [a,b]} \; |f(t) - p(t)|$$

- ightharpoonup If f is continuous, best approximation to f on [a,b] by polynomials of degree $\leq n$ exists and is unique
- ightharpoonup ... and $\lim_{n o\infty}
 ho_n(f)=0$ (Weierstrass theorem).

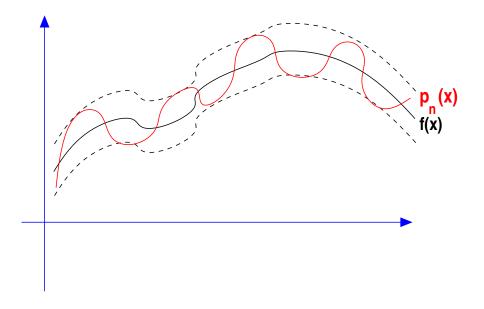
Question: How to find the best polynomial?

Answer: Chebyshev's equi-oscillation theorem.

Chebyshev equi-oscillation theorem: p_n is the best uniform approximation to f in [a,b] if and only if there are n+2 points $t_0 < t_1 < \ldots < t_{n+1}$ in [a,b] such that

$$f(t_j)-p_n(t_j)=c(-1)^j\|f-p_n\|_\infty$$
 with $c=\pm 1$

 $[p_n$ 'equi-oscillates' n+2 times around f]



Application: Chebyshev polynomials

Question: Among all monic polynomials of degree n+1 which one minimizes the infinity norm? Problem:

Minimize
$$\|t^{n+1}-a_nt^n-a_{n-1}t^{n-1}-\cdots-a_0\|_\infty$$

Reformulation: Find the best uniform approximation to t^{n+1} by polynomials p of degree $\leq n$.

 $ightharpoonup t^{n+1} - p(t)$ should be a polynomial of degree n+1 which equi-oscillates n+2 times.

Define Chebyshev polynomials:

$$C_k(t) = \cos(k\cos^{-1}t)$$
 for $k=0,1,...$, and $t \in [-1,1]$

- \blacktriangleright Observation: C_k is a polynomial of degree k, because:
- \blacktriangleright the C_k 's satisfy the three-term recurrence :

$$C_{k+1}(t) = 2xC_k(t) - C_{k-1}(t)$$

with
$$C_0(t)=1$$
, $C_1(t)=t$.

- Show the above recurrence relation
- leftright Compute C_2, C_3, \ldots, C_8

$$C_k(t)=\operatorname{ch}(k\operatorname{ch}^{-1}(t))$$

- $ightharpoonup C_k$ Equi-Oscillates k+1 times around zero.
- ightharpoonup Normalize C_{n+1} so that leading coefficient is 1

The minimum of $\|t^{n+1}-p(t)\|_\infty$ over $p\in\mathbb{P}_n$ is achieved when $t^{n+1}-p(t)=rac{1}{2^n}C_{n+1}(t)$.

Another important result:

Let $[\alpha, \beta]$ be a non-empty interval in \mathbb{R} and let γ be any real scalar outside the interval $[\alpha, \beta]$. Then the minimum

$$\min_{p \in \mathbb{P}_k, p(\gamma) = 1} \; \max_{t \in [lpha, eta]} |p(t)|$$

is reached by the polynomial:
$$\hat{C}_k(t) \equiv rac{C_k \left(1 + 2rac{lpha - t}{eta - lpha}
ight)}{C_k \left(1 + 2rac{lpha - \gamma}{eta - lpha}
ight)}.$$

Convergence Theory for CG

- Approximation of the form $x=x_0+p_{m-1}(A)r_0$. with $x_0=$ initial guess, $r_0=b-Ax_0$;
- ightharpoonup Recall property: $|x_m|$ minimizes $||x-x_*||_A$ over x_0+K_m
- Consequence: Standard result

Let $oldsymbol{x_m} = oldsymbol{m}$ -th CG iterate, $oldsymbol{x_*} = ext{exact}$ solution and

$$\eta = rac{\lambda_{min}}{\lambda_{max} - \lambda_{min}}$$

Then:
$$\|x_* - x_m\|_A \leq rac{\|x_* - x_0\|_A}{C_m(1+2\eta)}$$

where $C_m =$ Chebyshev polynomial of degree m.

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 \blacktriangleright Alternative expression. From $C_k = ch(kch^{-1}(t))$:

$$C_m(t)=rac{1}{2}\left[\left(t+\sqrt{t^2-1}
ight)^m+\left(t+\sqrt{t^2-1}
ight)^{-m}
ight] \ \geq rac{1}{2}\left(t+\sqrt{t^2-1}
ight)^m$$
 . Then:

$$egin{split} C_m(1+2\eta) & \geq rac{1}{2} \left(1 + 2\eta + \sqrt{(1+2\eta)^2 - 1}
ight)^m \ & \geq rac{1}{2} \left(1 + 2\eta + 2\sqrt{\eta(\eta+1)}
ight)^m. \end{split}$$

Next notice that:

$$egin{aligned} 1 + 2\eta + 2\sqrt{\eta(\eta+1)} &= \left(\sqrt{\eta} + \sqrt{\eta+1}
ight)^2 \ &= rac{\left(\sqrt{\lambda_{min}} + \sqrt{\lambda_{max}}
ight)^2}{\lambda_{max} - \lambda_{min}} \end{aligned}$$

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$$=rac{\sqrt{\lambda_{max}}+\sqrt{\lambda_{min}}}{\sqrt{\lambda_{max}}-\sqrt{\lambda_{min}}} \ =rac{\sqrt{\kappa}+1}{\sqrt{\kappa}-1}$$

where
$$\kappa = \kappa_2(A) = \lambda_{max}/\lambda_{min}$$
.

Substituting this in previous result yields

$$\|x_* - x_m\|_A \leq 2 \left[rac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1}
ight]^m \|x_* - x_0\|_A.$$

Compare with steepest descent!

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Theory for Nonhermitian case

- Much more difficult!
- No convincing results on 'global convergence' for most algorithms: FOM, GMRES(k), BiCG (to be seen) etc..
- Can get a general a-priori a-posteriori error bound

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Convergence results for nonsymmetric case

- Methods based on minimum residual better understood.
- If $(A + A^T)$ is positive definite $((Ax, x) > 0 \ \forall x \neq 0)$, all minimum residual-type methods (ORTHOMIN, ORTHODIR, GCR, GMRES,...), + their restarted and truncated versions, converge.
- ightharpoonup Convergence results based on comparison with one-dim. MR [Eisenstat, Elman, Schultz 1982] ightharpoonup not sharp.

MR-type methods: if $A=X\Lambda X^{-1}$, Λ diagonal, then

$$\|b-Ax_m\|_2 \leq \mathsf{Cond}_2(X) \min_{p \in \mathcal{P}_{m-1}, p(0)=1} \ \max_{\pmb{\lambda} \in \Lambda(A)} |p(\pmb{\lambda})|$$

($\mathcal{P}_{m-1} \equiv$ set of polynomials of degree $\leq m-1$, $\Lambda(A) \equiv$ spectrum of A)

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