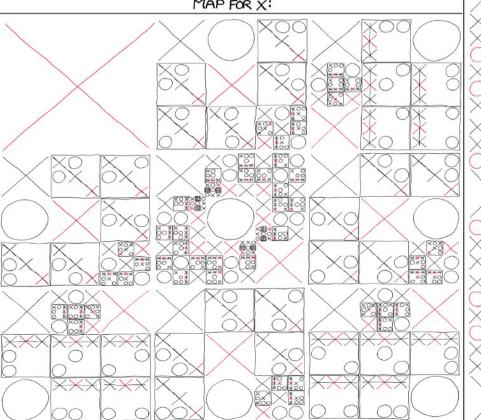
## Minimax (Ch. 5-5.3)

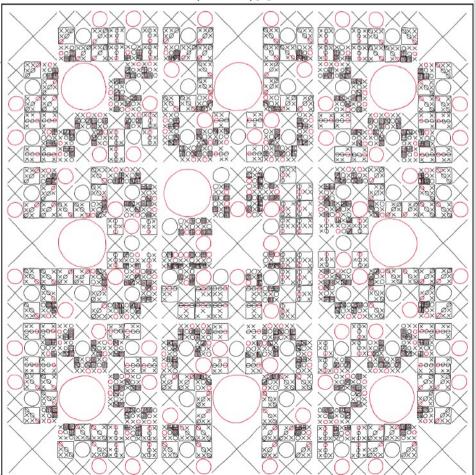
#### COMPLETE MAP OF OPTIMAL TIC-TAC-TOE MOVES

YOUR MOVE IS GIVEN BY THE POSITION OF THE LARGEST RED SYMBOL ON THE GRID. WHEN YOUR OPPONENT PICKS A MOVE, ZOOM IN ON THE REGION OF THE GRID WHERE THEY WENT. REPEAT.

MAP FOR X:



MAP FOR O:



#### Announcements

Homework 1 solutions posted

Test next week (9<sup>th</sup>) -Covers up to and including HW2 (all search, Ch. 1-4)

## Single-agent

So far we have look at how a single agent can search the environment based on its actions

Now we will extend this to cases where you are not the only one changing the state (i.e. multi-agent)

The first thing we have to do is figure out how to represent these types of problems

## Multi-agent (competitive)

Most games only have a utility (or value) associated with the end of the game (leaf node)

So instead of having a "goal" state (with possibly infinite actions), we will assume:

(1) All actions eventually lead to terminal state (i.e. a leaf in the tree)

(2) We know the value (utility) only at leaves

# Multi-agent (competitive)

For now we will focus on <u>zero-sum</u> two-player games, which means a loss for one person is a gain for another

Betting is a good example of this: If I win I get \$5 (from you), if you win you get \$1 (from me). My gain corresponds to your loss

<u>Zero-sum</u> does not technically need to add to zero, just that the sum of scores is constant

# Multi-agent (competitive)

Zero sum games mean rather than representing outcomes as: [Me=5, You =-5]

We can represent it with a single number: [Me=5], as we know: Me+You = 0 (or some c)

This lets us write a single outcome which "Me" wants to maximize and "You" wants to minimize

Thus the root (our agent) will start with a maximizing node, the the opponent will get minimizing noes, then back to max... repeat...

This alternation of maximums and minimums is called <u>minimax</u>

I will use  $\triangle$  to denote nodes that try to maximize and  $\nabla$  for minimizing nodes

Let's say you are treating a friend to lunch. You choose either: Shuang Cheng or Afro Deli

The friend always orders the most inexpensive item, you want to treat your friend to best food

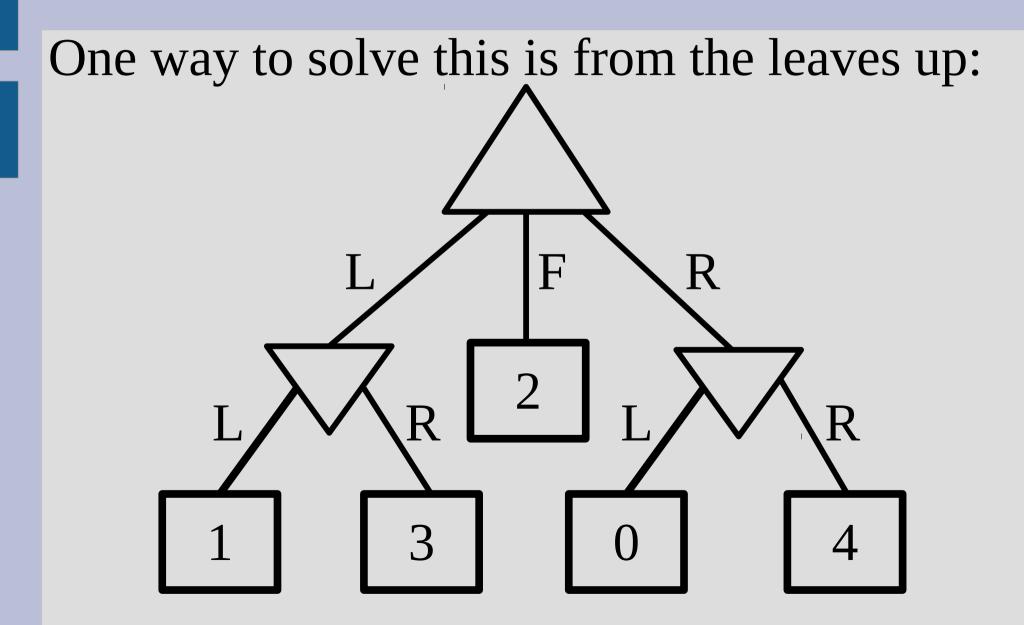
Which restaurant should you go to? Menus: Shuang Cheng: Fried Rice=\$10.25, Lo Mein=\$8.55 Afro Deli: Cheeseburger=\$6.25, Wrap=\$8.74

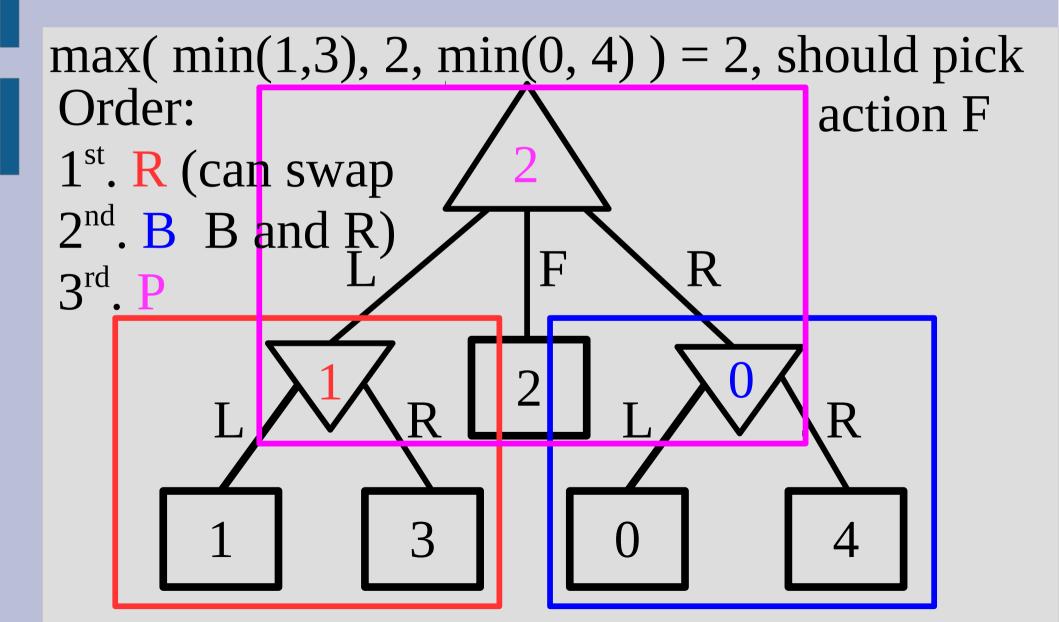


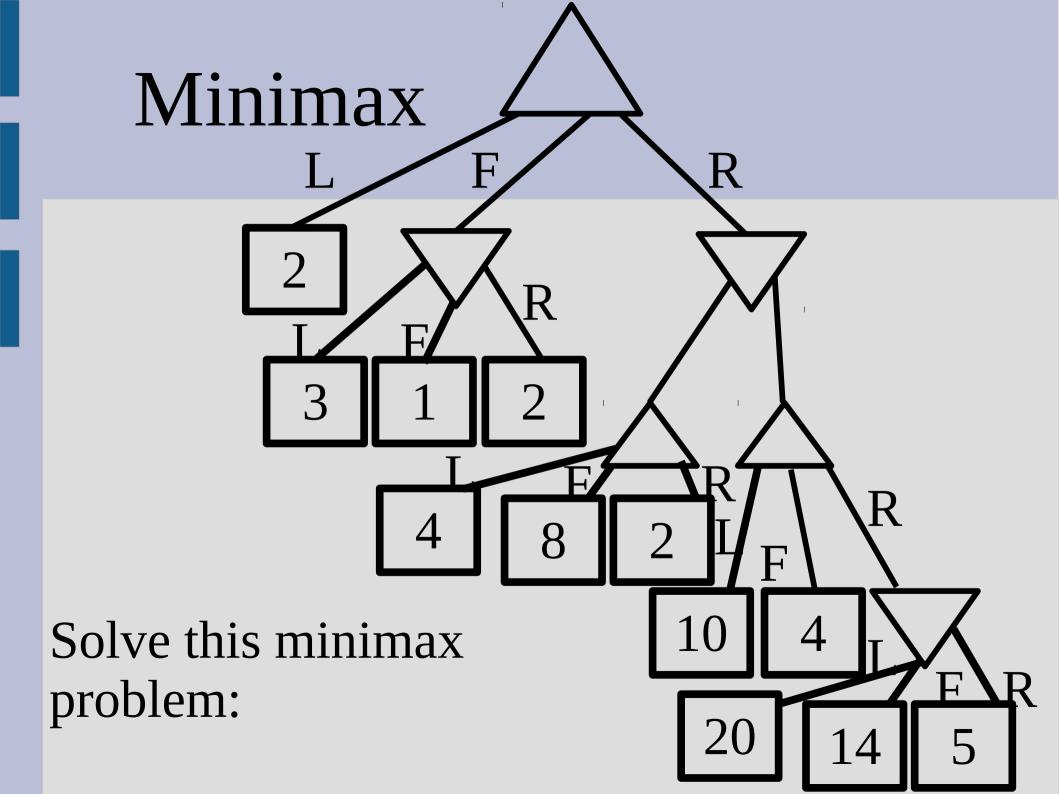
You could phrase this problem as a set of maximum and minimums as: max( min(8.55, 10.25), min(6.25, 8.55) )

... which corresponds to: max( Shuang Cheng choice, Afro Deli choice)

If our goal is to spend the most money on our friend, we should go to Shuang Cheng







This representation works, but even in small games you can get a very large search tree

For example, tic-tac-toe has about 9! actions to search (or about 300,000 nodes)

Larger problems (like chess or go) are not feasible for this approach (more on this next class)

"Pruning" in real life:

Snip branch



#### "Pruning" in CSCI trees: 6 MAX MIN 7 5 6 MAX Snip branch 6 MIN 4 5 36697 6 5 9 8 MAX

However, we can get the same answer with searching less by using efficient "pruning"

It is possible to prune a minimax search that will never "accidentally" prune the optimal solution

A popular technique for doing this is called <u>alpha-beta pruning</u> (see next slide)

Consider if we were finding the following: max(5, min(3, 19))

There is a "short circuit evaluation" for this, namely the value of 19 does not matter

 $min(3, x) \le 3$  for all x Thus max(5, min(3,x)) = 5 for any x

Alpha-beta pruning would not search x above

If when checking a min-node, we ever find a value less than the parent's "best" value, we can stop searching this branch

2

R

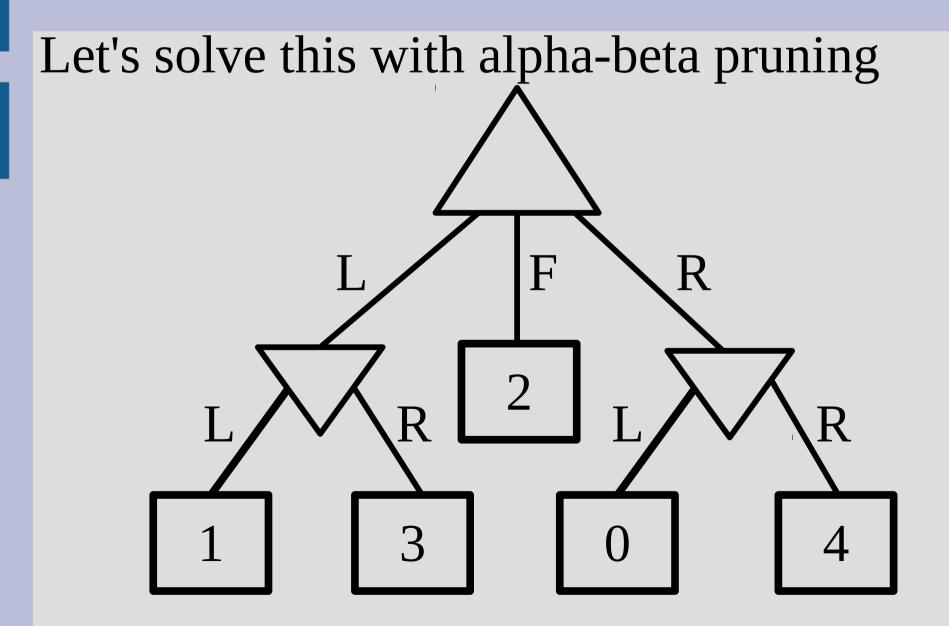
Parent's best so far = 2

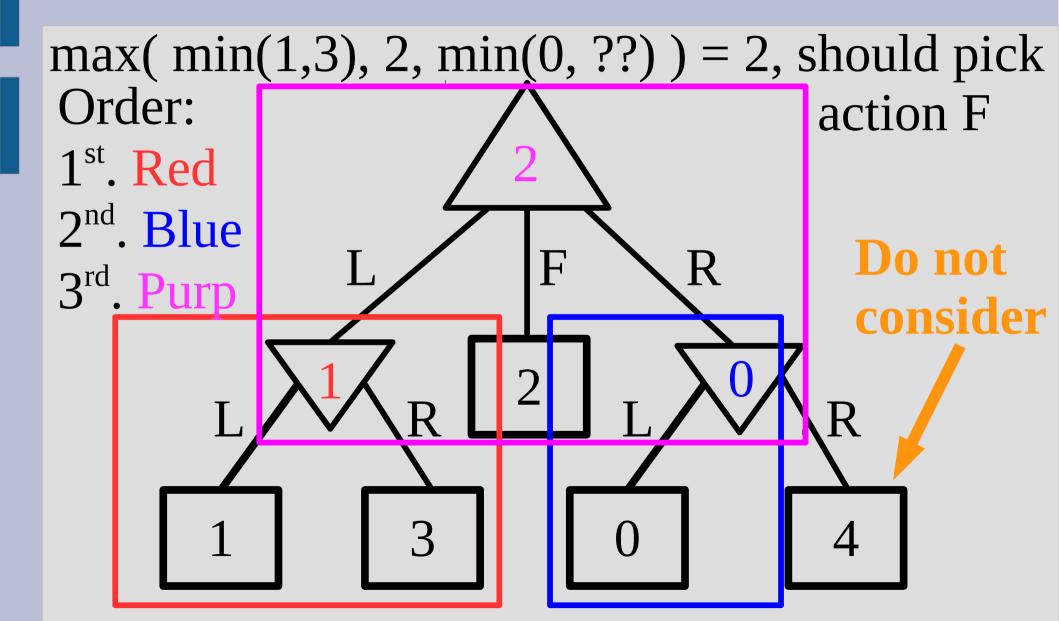
Child's worst = 0

STOP

In the previous slide, "best" is the "alpha" in the alpha-beta pruning (Similarly the "worst" in a min-node is "beta")

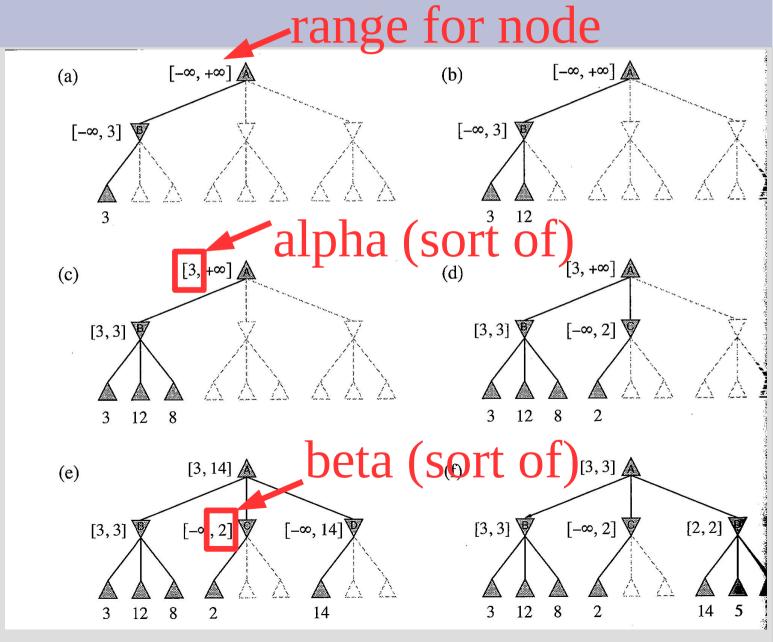
Alpha-beta pruning algorithm: Do minimax as normal, except: min node: if parent's "best" value greater than current node, stop & tell parent current value max node: if parent's "worst" value less than current node, stop search and return current

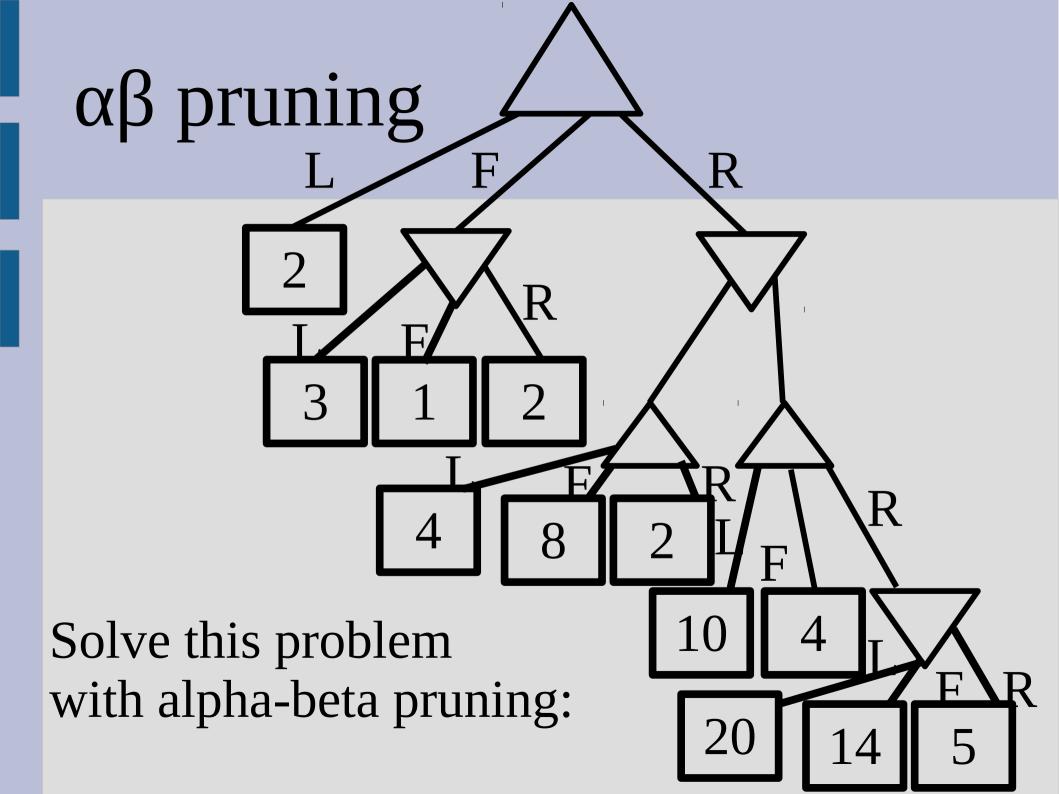




I think the book is confusing about alpha-beta, especially Figure 5.5

\rantOn





In general, alpha-beta pruning allows you to search to a depth 2d for the minimax search cost of depth d

So if minimax needs to find: O(b<sup>m</sup>) Then, alpha-beta searches: O(b<sup>m/2</sup>)

This is exponentially better, but the worst case is the same as minimax

Ideally you would want to put your best (largest for max, smallest for min) actions first

This way you can prune more of the tree as a min node stops more often for larger "best"

Obviously you do not know the best move, (otherwise why are you searching?) but some effort into guessing goes a long way (i.e. exponentially less states)

### Side note:

In alpha-beta pruning, the heuristic for guess which move is best can be complex, as you can greatly effect pruning

While for A\* search, the heuristic had to be very fast to be useful (otherwise computing the heuristic would take longer than the original search)