

APPLICATIONS OF GRAPH LAPLACEANS: Graph Embeddings, and Dimension Reduction

- Graph Embeddings, vertex embeddings . The problem
- Use of Graph Laplaceans, Laplacean Eigenmaps
- Use of similarity graphs: Locally Linear Embeddings
- Explicit dimension reduction method: PCA
- Explicit graph-based dimension reduction method: LLP, ONPP.

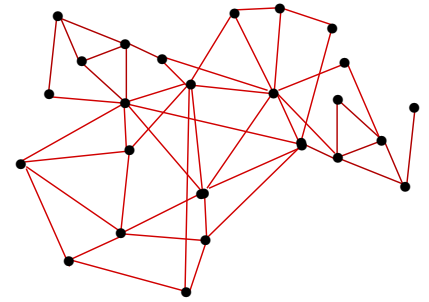
Graph embeddings

Vertex embedding: map every vertex x_i to a vector $y_i \in \mathbb{R}^d$

- Trivial use: visualize a graph ($d = 2$)
- Wish: mapping should preserve *similarities* in graph.
- Many applications [clustering, finding missing link, semi-supervised learning, community detection, ...]
- We will see two *nonlinear* classical methods: Eigenmaps, LLE
...
- ... and two linear (explicit) ones.

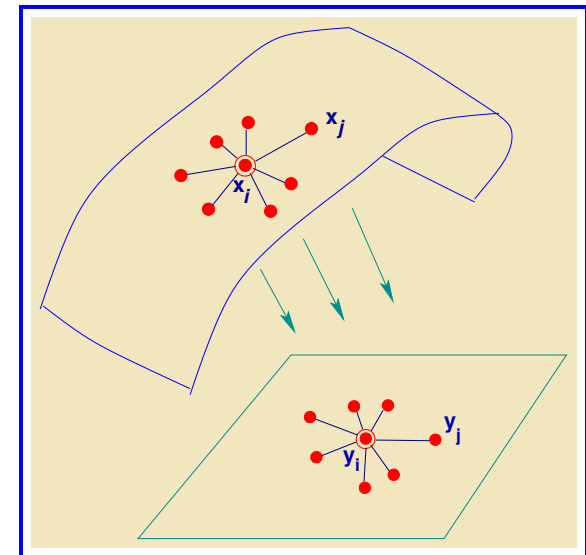
Given: a graph that models some data points x_1, x_2, \dots, x_n
[simplest case: a kNN graph of x_1, x_2, \dots, x_n]

Data: $X = [x_1, x_2, \dots, x_n]$ \longrightarrow Graph:



➤ Graph captures similarities, closeness, ..., in data

Objective: Build a mapping of each vertex i to a data point $y_i \in \mathbb{R}^d$



➤ Many methods to do this. **Eigenmaps** is one of the best known

- Eigenmaps uses the *graph Laplacean*
- Recall: Graph Laplacean is a matrix defined by :

$$L = D - W$$

$$\begin{cases} w_{ij} \geq 0 & \text{if } j \in Adj(i) \\ w_{ij} = 0 & \text{else} \end{cases} \quad D = \text{diag} \left[d_{ii} = \sum_{j \neq i} w_{ij} \right]$$

with $Adj(i)$ = neighborhood of i (excludes i)

- Remember that vertex i represents data item x_i . We will use i or x_i to refer to the vertex.
- We will find the y_i 's by solving an optimization problem.

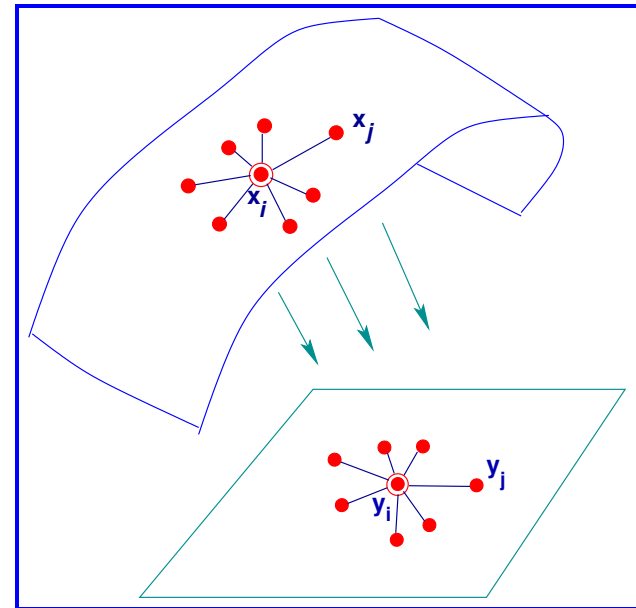
The Laplacean eigenmaps approach

Laplacean Eigenmaps [Belkin-Niyogi '01] *minimizes*

$$\mathcal{F}(Y) = \sum_{i,j=1}^n w_{ij} \|y_i - y_j\|^2 \quad \text{subject to} \quad YDY^T = I$$

Motivation: if $\|x_i - x_j\|$ is small (orig. data), we want $\|y_i - y_j\|$ to be also small (low-Dim. data)

- Original data used indirectly through its graph
- Objective function can be translated to a trace (see Property 3 in Lecture notes 9) and will yield a sparse eigenvalue problem



- Problem translates to:

$$\begin{cases} \min_{Y \in \mathbb{R}^{d \times n}} & \text{Tr} \left[Y(D - W)Y^\top \right] \\ YD Y^\top = I \end{cases} .$$

- Solution (sort eigenvalues increasingly):

$$(D - W)u_i = \lambda_i D u_i ; \quad y_i = u_i^\top ; \quad i = 1, \dots, d$$

- An $n \times n$ sparse eigenvalue problem [In 'sample' space]

- Note: can assume $D = I$. Amounts to rescaling data. Problem becomes

$$(I - W)u_i = \lambda_i u_i ; \quad y_i = u_i^\top ; \quad i = 1, \dots, d$$

Locally Linear Embedding (Roweis-Saul-00)

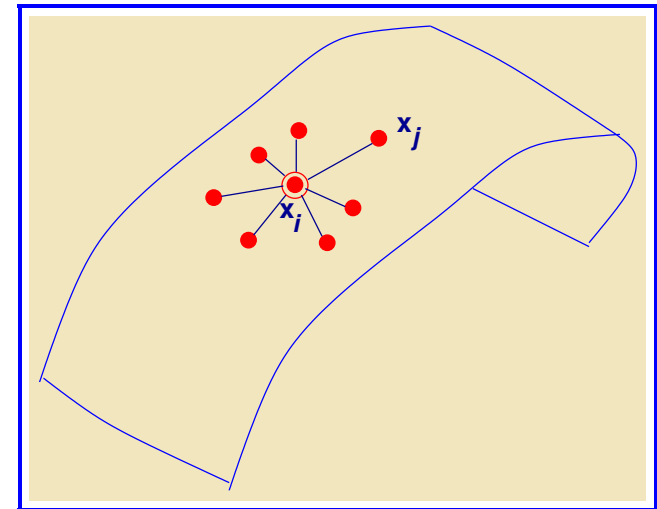
- LLE is very similar to Eigenmaps. Main differences:
 - 1) Graph Laplacean matrix is replaced by an 'affinity' graph
 - 2) Objective function is changed: want to preserve graph

1. Graph: Each x_i is written as a convex combination of its k nearest neighbors:

$$x_i \approx \sum_{j \in N_i} w_{ij} x_j, \quad \sum_{j \in N_i} w_{ij} = 1$$

➤ Optimal weights computed ('local calculation') by minimizing

$$\|x_i - \sum w_{ij} x_j\| \quad \text{for } i = 1, \dots, n$$



2. Mapping:

The \mathbf{y}_i 's should obey the same 'affinity' as \mathbf{x}_i 's \rightsquigarrow

Minimize:

$$\sum_i \left\| \mathbf{y}_i - \sum_j w_{ij} \mathbf{y}_j \right\|^2 \quad \text{subject to: } \mathbf{Y} \mathbf{1} = \mathbf{0}, \quad \mathbf{Y} \mathbf{Y}^\top = \mathbf{I}$$

Solution:

$$(\mathbf{I} - \mathbf{W}^\top)(\mathbf{I} - \mathbf{W})\mathbf{u}_i = \lambda_i \mathbf{u}_i; \quad \mathbf{y}_i = \mathbf{u}_i^\top.$$

➤ $(\mathbf{I} - \mathbf{W}^\top)(\mathbf{I} - \mathbf{W})$ replaces the graph Laplacean of eigenmaps

Implicit vs explicit mappings

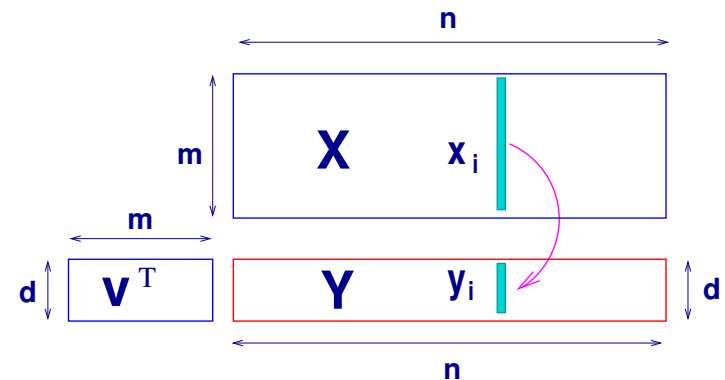
➤ Background: Principal Component Analysis (PCA)

Dimension reduction via PCA: We are **given** a data set $X = [x_1, x_2, \dots, x_n]$, and **want** a linear mapping from X to Y , expressed as:

$$Y = V^T X$$

$$X \in \mathbb{R}^{m \times n}; \quad V \in \mathbb{R}^{m \times d}$$
$$\rightarrow Y \in \mathbb{R}^{d \times n}$$

➤ m -dimens. objects (x_i) 'flattened' to d -dimens. space (y_i)



➤ In PCA V is orthogonal ($V^T V = I$)

- In *Principal Component Analysis* $V \in \mathbb{R}^{m \times d}$ is computed to maximize variance of projected data:

$$\max_{V; V^T V = I} \sum_{i=1}^d \left\| y_i - \frac{1}{n} \sum_{j=1}^n y_j \right\|_2^2, \quad y_i = V^T x_i.$$

- Leads to maximizing

$$\text{Tr} [V^T (X - \mu e^T)(X - \mu e^T)^T V], \quad \mu = \frac{1}{n} \sum_{i=1}^n x_i$$

- Solution $V = \{ \text{dominant eigenvectors} \}$ of the covariance matrix

Explicit (linear) vs. Implicit (nonlinear) mappings:

- In PCA the mapping Φ from high-dimensional space (\mathbb{R}^m) to low-dimensional space (\mathbb{R}^d) is explicitly known:

$$y = \Phi(x) \equiv V^T x$$

- In Eigenmaps and LLE we only know

$$y_i = \phi(x_i), i = 1, \dots, n$$

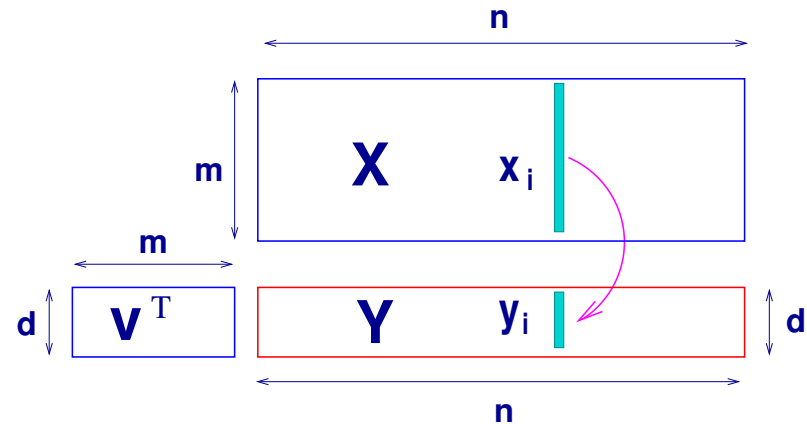
- Mapping ϕ is now implicit: Very difficult to compute $\phi(x)$ for an x that is not in the sample (i.e., not one of the x_i 's)
- Inconvenient for classification. Thus is known as the “The out-of-sample extension” problem

Locally Preserving Projections (He-Niyogi-03)

➤ LPP is a **linear** dimensionality reduction technique

➤ Recall the setting:

Want $V \in \mathbb{R}^{m \times d}$; $Y = V^T X$



➤ Starts with the same neighborhood graph as Eigenmaps: $L \equiv D - W = \text{graph 'Laplacean'}$; with $D \equiv \text{diag}(\{\sum_i w_{ij}\})$.

- Optimization problem is to solve

$$\min_{Y \in \mathbb{R}^{d \times n}, YDY^\top = I} \sum_{i,j} w_{ij} \|y_i - y_j\|^2, \quad Y = V^\top X.$$

- Difference with eigenmaps: Y is an explicit projection of X
- Solution (sort eigenvalues increasingly)

$$XLX^\top v_i = \lambda_i XDX^\top v_i \quad y_{i,:} = v_i^\top X$$

- Note: essentially same method in [Koren-Carmel'04] called 'weighted PCA' [viewed from the angle of improving PCA]

ONPP (Kokopoulou and YS '05)

- Orthogonal Neighborhood Preserving Projections
- A linear (orthogonal) version of LLE obtained by writing \mathbf{Y} in the form $\mathbf{Y} = \mathbf{V}^\top \mathbf{X}$
- Same graph as LLE. Objective: preserve the affinity graph (as in LLE) *but* with the constraint $\mathbf{Y} = \mathbf{V}^\top \mathbf{X}$
- Problem solved to obtain mapping:

$$\min_{\mathbf{V}} \text{Tr} \left[\mathbf{V}^\top \mathbf{X} (\mathbf{I} - \mathbf{W}^\top) (\mathbf{I} - \mathbf{W}) \mathbf{X}^\top \mathbf{V} \right]$$

s.t. $\mathbf{V}^\top \mathbf{V} = \mathbf{I}$

- In LLE replace $\mathbf{V}^\top \mathbf{X}$ by \mathbf{Y}

More recent methods

➤ Quite a bit of recent work - e.g., methods: node2vec, DeepWalk, GraRep,

See the following papers:

[1] *William L. Hamilton, Rex Ying, and Jure Leskovec Representation Learning on Graphs: Methods and Applications* arXiv:1709.05584v3

[2] *Shaosheng Cao, Wei Lu, and Qionghai Xu GraRep: Learning Graph Representations with Global Structural Information*, CIKM, ACM Conference on Information and Knowledge Management, 24

[3] *Amr Ahmed, Nino Shervashidze, and Shravan Narayanamurthy, Distributed Large-scale Natural Graph Factorization* [Proc. WWW 2013, May 13-17, 2013, Rio de Janeiro, Brazil]

... among many others