

$$\boxed{\text{Ex 1}} \text{ Solution of System } \begin{pmatrix} 5 & 10 & 25 \\ 1 & 1 & 1 \\ 0 & 10 & 25 \end{pmatrix} \begin{pmatrix} x_n \\ x_d \\ x_q \end{pmatrix} = \begin{pmatrix} 145 \\ 12 \\ 125 \end{pmatrix}$$

**Solution:** You will find:  $x_n = 4$ ,  $x_d = 5$ ,  $x_q = 3$ .

$$\boxed{\text{Ex 3}} \quad (A^T)^T = ??$$

$$\text{Solution: } (A^T)^T = A$$

$$\boxed{\text{Ex 4}} \quad (AB)^T = ??$$

$$\text{Solution: } (AB)^T = B^T A^T$$

$$\boxed{\text{Ex 5}} \quad (A^H)^H = ??$$

$$\text{Solution: } (A^H)^H = A$$

$$\boxed{\text{Ex 6}} \quad (A^H)^T = ??$$

$$\text{Solution: } (A^H)^T = \bar{A}$$

$$\boxed{\text{Ex 7}} \quad (ABC)^T = ??$$

$$\text{Solution: } (ABC)^T = C^T B^T A^T$$

$$\boxed{\text{Ex 8}} \quad \text{True/False: } (AB)C = A(BC)$$

**Solution:**  $\rightarrow$  True

Q9 True/False:  $AB = BA$       **Solution:**  $\rightarrow$  false

Q10 True/False:  $AA^T = A^T A$       **Solution:**  $\rightarrow$  false in general

Q12 Complexity? [number of multiplications and additions for matrix multiply]

**Solution:** Let  $A \in \mathbb{R}^{m \times n}$  and  $B \in \mathbb{R}^{n \times p}$ . Then the product  $AB$  requires  $2mnp$  operations (there are  $mp$  entries in all and each of them requires  $2n$  operations).  $\square$

Q13 What happens to these 3 different approaches to matrix-matrix multiplication when  $B$  has one column ( $p = 1$ )?

**Solution:** In the first:  $C_{:,j}$  the  $j$ -th column of  $C$  is a linear combination of the columns of  $A$ . This is the usual matrix-vector product.

In the second:  $C_{i,:}$  is just a number which is the inner product of the  $i$ -th row of  $A$  with the column  $B$ .

The 3rd formula will give the exact same expression as the first.  $\square$

Q14 Characterize the matrices  $AA^T$  and  $A^T A$  when  $A$  is of dimension  $n \times 1$ .

**Solution:** When  $A \in \mathbb{R}^{n \times 1}$  then  $AA^T$  is a rank-one  $n \times n$  matrix and  $A^T A$  is a scalar: the inner product of the column  $A$  with itself.  $\square$

**15** **16** Show that  $A \in \mathbb{R}^{m \times n}$  is of rank one iff [if and only if] there exist two nonzero vectors  $u \in \mathbb{R}^m$  and  $v \in \mathbb{R}^n$  such that

$$A = uv^T.$$

What are the eigenvalues and eigenvectors of  $A$ ?

**Solution:** (a)

← First we show that: When both  $u$  and  $v$  are nonzero vectors then the rank of a matrix of the matrix  $A = uv^T$  is one. The range of  $A$  is the set of all vectors of the form

$$y = Ax = uv^T x = (v^T x)u$$

since  $u$  is a nonzero vector, and not all vectors  $v^T x$  are zero (because  $v \neq 0$ ) then this space is

of dimension 1.

→ Next we show that: If  $A$  is of rank one then there exist nonzero vectors  $u, v$  such that  $A = uv^T$ . If  $A$  is of rank one, then  $\text{Ran}(A) = \text{Span}\{u\}$  for some nonzero vector  $u$ . So for every vector  $x$ , the vector  $Ax$  is a multiple of  $u$ . Let  $e_1, e_2, \dots, e_n$  the vectors of the canonical basis of  $\mathbb{R}^n$  and let  $\nu_1, \nu_2, \dots, \nu_n$  the scalars such that  $Ae_i = \nu_i u$ . Define  $v = [\nu_1, \nu_2, \dots, \nu_n]^T$ . Then  $A = uv^T$  because the matrices  $A$  and  $uv^T$  have the same columns. (Note that the  $j$ -th column of  $A$  is the vector  $Ae_j$ ). In addition,  $v \neq 0$  otherwise  $A = 0$  which would be a contradiction because  $\text{rank}(A) = 1$ .

(b) Eigenvalues /vectors

Write  $Ax = \lambda x$  then notice that this means  $(v^T x)u = \lambda x$  so either  $v^T x = 0$  and  $\lambda = 0$  or  $x = u$  and  $\lambda = v^T u$ . Two eigenvalues: 0 and  $v^T u$ .  $\square$

17 Is it true that

$$\text{rank}(\mathbf{A}) = \text{rank}(\bar{\mathbf{A}}) = \text{rank}(\mathbf{A}^T) = \text{rank}(\mathbf{A}^H) ?$$

**Solution:**

*The answer is yes and it follows from the fact that the ranks of  $\mathbf{A}$  and  $\mathbf{A}^T$  are the same and the ranks of  $\mathbf{A}$  and  $\bar{\mathbf{A}}$  are also the same.*

*It is known that  $\text{rank}(\mathbf{A}) = \text{rank}(\mathbf{A}^T)$ . We now compare the ranks of  $\mathbf{A}$  and  $\bar{\mathbf{A}}$  (everything is considered to be complex).*

*The important property that is used is that if a set of vectors is linearly independent then so is its conjugate. [convince yourself of this by looking at material from 2033]. If  $\mathbf{A}$  has rank  $r$  and for example its first  $r$  columns are the basis of the range, the the same  $r$  columns of  $\bar{\mathbf{A}}$  are also linearly independent. So  $\text{rank}(\bar{\mathbf{A}}) \geq \text{rank}(\mathbf{A})$ . Now you can use a similar argument to show that  $\text{rank}(\mathbf{A}) \geq \text{rank}(\bar{\mathbf{A}})$ . Therefore the ranks are the same.  $\square$*

**21** Eigenvalues of two similar matrices  $A$  and  $B$  are the same. What about eigenvectors?

**Solution:** If  $Au = \lambda u$  then  $XBX^{-1}u = \lambda u \rightarrow B(X^{-1}u) = \lambda(X^{-1}u) \rightarrow \lambda$  is an eigenvalue of  $B$  with eigenvector  $X^{-1}u$  (note the vector  $X^{-1}u$  cannot be equal to zero because  $u \neq 0$ .)  $\square$

**22** Given a polynomial  $p(t)$  how would you define  $p(A)$ ?

**Solution:** If  $p(t) = \alpha_0 + \alpha_1 t + \alpha_2 t^2 + \dots + \alpha_k t^k$  then

$$p(A) = \alpha_0 I + \alpha_1 A + \alpha_2 A^2 + \dots + \alpha_k A^k$$

where

$$A^j = \underbrace{A \times A \times \dots \times A}_{j \text{ times}}$$

$\square$

**23** Given a function  $f(t)$  (e.g.,  $e^t$ ) how would you define  $f(A)$ ? [You may limit yourself to the case when  $A$  is diagonalizable]

**Solution:** The easiest way would be through the Taylor series expansion..

$$f(A) = f(0)I + \frac{f'(0)}{1!}A + \frac{f''(0)}{2!}A^2 \dots \frac{f^{(k)}(0)}{k!}A^k + \dots$$

However, this will require a justification: Will this expression 'converge' as the number of terms goes to infinity? This is where norms are useful. We will revisit this in next set.  $\square$

**24** If  $A$  is nonsingular what are the eigenvalues/eigenvectors of  $A^{-1}$ ?

**Solution:** Assume that  $Au = \lambda u$ . Multiply both sides by the inverse of  $A$ :  $u = \lambda A^{-1}u$  - then by the inverse of  $\lambda$ :  $\lambda^{-1}u = A^{-1}u$ . Therefore,  $1/\lambda$  is an eigenvalue and  $u$  is an associated eigenvector.  $\square$

**25** What are the eigenvalues/eigenvectors of  $A^k$  for a given integer power  $k$ ?

**Solution:** Assume that  $Au = \lambda u$ . Multiply both sides by  $A$  and repeat  $k$  times. You will get  $A^k u = \lambda^k u$ . Therefore,  $\lambda^k$  is an eigenvalue of  $A^k$  and  $u$  is an associated eigenvector.  $\square$

**26** What are the eigenvalues/eigenvectors of  $p(A)$  for a polynomial  $p$ ?

**Solution:** Using the previous result you can show that  $p(\lambda)$  is an eigenvalue of  $p(A)$  and  $u$  is an associated eigenvector.  $\square$

**27** What are the eigenvalues/eigenvectors of  $f(A)$  for a function  $f$ ? [Diagonalizable case]

**Solution:** This will require using the diagonalized form of  $A$ :  $A = XDX^{-1}$ . With this  $f(A) = Xf(D)X^{-1}$ . It becomes clear that the eigenvalues are the diagonal entries of  $f(D)$ , i.e., the values  $f(\lambda_i)$  for  $i = 1, \dots, n$ . As for the eigenvectors - recall that they are the columns of the  $X$  matrix in the diagonalized form - And  $X$  is the same for  $A$  and  $f(A)$ . So the eigenvectors are the same.  $\square$

**28** For two  $n \times n$  matrices  $A$  and  $B$  are the eigenvalues of  $AB$  and  $BA$  the same?

**Solution:** We will show that if  $\lambda$  is an eigenvalue of  $AB$  then it is also an eigenvalue of  $BA$ . Assume that  $ABu = \lambda u$  and multiply both sides by  $B$ . Then  $BABu = \lambda Bu$  - which we write in the form:  $BAv = \lambda v$  where  $v = Bu$ . In the situation when  $v \neq 0$ , we clearly see that  $\lambda$  is a nonzero eigenvalue of  $BA$  with the associated eigenvector  $v$ . We now deal with the case when  $v = 0$ . In this case, since  $ABu = \lambda u$ , and  $u \neq 0$  we must have  $\lambda = 0$ . However,



clearly  $\lambda = 0$  is also an eigenvalue of  $BA$  because  $\det(BA) = \det(AB) = 0$ .

We can similarly show that any eigenvalue of  $BA$  are also eigenvalues of  $AB$  by interchanging the roles of  $A$  and  $B$ . This completes the proof  $\square$

**30** Trace, spectral radius, and determinant of  $A = \begin{pmatrix} 2 & 1 \\ 3 & 0 \end{pmatrix}$ .

**Solution:** Trace is 2, determinant is  $-3$ . Eigenvalues are 3,  $-1$  so  $\rho(A) = 3$ .  $\square$

**31** What is the inverse of a unitary (complex) or orthogonal (real) matrix?

**Solution:** If  $Q$  is unitary then  $Q^{-1} = Q^H$ .  $\square$

**32** What can you say about the diagonal entries of a skew-symmetric (real) matrix?


**Solution:** They must be equal to zero.  $\square$

**33** What can you say about the diagonal entries of a Hermitian (complex) matrix?

**Solution:** We must have  $a_{ii} = \bar{a}_{ii}$ . Therefore  $a_{ii}$  must be real.  $\square$

 34 What can you say about the diagonal entries of a skew-Hermitian (complex) matrix?

**Solution:** We must have  $a_{ii} = -\bar{a}_{ii}$ . Therefore  $a_{ii}$  must be purely imaginary.

 35 Which matrices of the following type are also normal: real symmetric, real skew-symmetric, Hermitian, skew-Hermitian, complex symmetric, complex skew-symmetric matrices.

**Solution:** Real symmetric, real skew-symmetric, Hermitian, skew-Hermitian matrices are normal. Complex symmetric, complex skew-symmetric matrices are not necessarily normal.

 39 What does the matrix-vector product  $V\mathbf{a}$  represent?

**Solution:** If  $\mathbf{a} = [a_0, a_1, \dots, a_n]$  and  $p(t)$  is the  $n$ -th degree polynomial:

$$p(t) = a_0 + a_1t + a_2t^2 + \dots + a_nt^n$$

then  $V\mathbf{a}$  is a vector whose components are the values  $p(x_0), p(x_1), \dots, p(x_n)$ .

 40 Interpret the solution of the linear system  $V\mathbf{a} = \mathbf{y}$  where  $\mathbf{a}$  is the unknown. Sketch a 'fast' solution method based on this.

**Solution:** Given the previous exercise, the interpretation is that we are seeking a polynomial of degree  $n$  whose values at  $x_0, \dots, x_n$  are the components of the vector  $\mathbf{y}$ , i.e.,  $y_0, y_1, \dots, y_n$ . This is known as polynomial interpolation (see csci 5302). The polynomial can be determined by, e.g., the Newton table in  $O(n^2)$  operations.  $\square$