

GENERAL VECTOR SPACES AND SUBSPACES [4.1]

11-1

General vector spaces

- So far we have seen special spaces of vectors of n dimensions – denoted by \mathbb{R}^n .
- It is possible to define more general **vector spaces**

A vector space V over \mathbb{R} is a nonempty set with two operations:

- **Addition** denoted by '+'. For two vectors x and y , $x + y$ is a member of V
- **Multiplication by a scalar** For $\alpha \in \mathbb{R}$ and $x \in V$, αx is a member of V .


- In addition for V to be a vector space the following 8 axioms must be satisfied [note: order is different in text]

11-2

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11-2

1. Addition is commutative $u + v = v + u$
2. Addition is associative $u + (v + w) = (u + v) + w$
3. \exists zero vector denoted by 0 such that $\forall u$, $0 + u = u$
4. Any u has an opposite $-u$ such that $u + (-u) = 0$
5. $1u = u$ for any u
6. $(\alpha\beta)u = \alpha(\beta u)$
7. $(\alpha + \beta)u = \alpha u + \beta u$
8. $\alpha(u + v) = \alpha u + \alpha v$

 Show that the zero vector in Axiom 3 is unique, and the vector $-u$, ('negative of u '), in Axiom 4 is unique for each u in V .

11-3

Text: 4.1 – Vspaces

11-3

- For each u in V and scalar α we have

$$0u = 0 \quad \alpha 0 = 0 ; \quad -u = (-1)u .$$

Example: Let V be the set of all arrows (directed line segments) in three-dimensional space, with two arrows regarded as equal if they have the same length and point in the same direction. Define addition by the parallelogram rule, and for each v in V , define cv to be the arrow whose length is c times the length of v , pointing in the same direction as v if $c > 0$ and otherwise pointing in the opposite direction.

Note: The definition of V is geometric, using concepts of length and direction. No xyz -coordinate system is involved. An arrow of zero length is a single point and represents the zero vector. The negative of v is $(-1)v$.

- All axioms are verified

11-4

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11-4

More examples

- Set of vectors in \mathbb{R}^4 with second component equal to zero.
- Set of all polynomials of degree ≤ 3
- Set of all $m \times n$ matrices
- Set of all $n \times n$ upper triangular matrices

11-5

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11-5

Subspaces

- A subset H of vectors of V is a subspace if it is a vector space by itself. Formal definition:

- A subset H of vectors of V is a subspace if

1. H is **closed** for the addition, which means:

$$x + y \in H \quad \text{for any } x \in H, y \in H$$

2. H is **closed** for the scalar multiplication, which means:

$$\alpha x \in H \quad \text{for any } \alpha \in \mathbb{R}, x \in H$$

- Note: If H is a subspace then (1) 0 belongs to H and (2) For any $x \in H$, the vector $-x$ belongs to H

11-6

Text: 4.1 – Vspaces

11-6

- Every vector space is a subspace (of itself and possibly of other larger spaces).
- The set consisting of only the zero vector of V is a subspace of V , called the zero subspace. Notation: $\{0\}$.

Example: Polynomials of the form

$$p(t) = \alpha_2 t^2 + \alpha_3 t^3$$

form a subspace of the space of polynomials of degree ≤ 3


 Other examples: Examples 3 and 5 (sec. 4.1) from **text**


Example: Triangular matrices

11-7

Text: 4.1 – Vspaces

11-7

 Example 8 (sec. 4.1) in **text** is important

 Show that the set H of all vectors in \mathbb{R}^3 of the form $\{a + b, a - b, b\}$ is a subspace of \mathbb{R}^3 . [Hint: see example 11 from Sec. 4.1 of **text**]

- Recall: the term **linear combination** refers to a sum of scalar multiples of vectors, and $\text{span}\{v_1, \dots, v_p\}$ denotes the set of all vectors that can be written as linear combinations of v_1, \dots, v_p .

11-8

Text: 4.1 – Vspaces

11-8

A subspace spanned by a set

Theorem: If v_1, \dots, v_p are in a vector space V , then

$$\text{span}\{v_1, \dots, v_p\}$$

is a subspace of V .

➤ $\text{span}\{v_1, \dots, v_p\}$ is the subspace **spanned** (or **generated**) by $\{v_1, \dots, v_p\}$.

➤ Given any subspace H of V , a spanning (or generating) set for H is a set $\{v_1, \dots, v_p\}$ in H such that $H = \text{span}\{v_1, \dots, v_p\}$.

☐ Prove above theorem for $p = 2$, i.e., given v_1 and v_2 in a vector space V , then $H = \text{span}\{v_1, v_2\}$ is a subspace of V . [Hint: show that H is closed for '+' and for scalar multiplication]

NULL SPACES AND COLUMN SPACES [4.2]

Null space of a matrix

Definition: The null space of an $m \times n$ matrix A , written as $\text{Nul}(A)$, is the set of all solutions of the homogeneous equation $Ax = 0$. In set notation,

$$\text{Nul}(A) = \{x : x \in \mathbb{R}^n \text{ and } Ax = 0\}.$$

Theorem: The null space of an $m \times n$ matrix A is a subspace of \mathbb{R}^n

➤ Equivalently, the set of all solutions to a system $Ax = 0$ of m homogeneous linear equations in n unknowns is a subspace of \mathbb{R}^n

Proof: $\text{Nul}(A)$ is by definition a subset of \mathbb{R}^n . Must show: $\text{Nul}(A)$ closed under + and multipl. by scalars.

➤ Take u and v any two vectors in $\text{Nul}(A)$. Then $Au = 0$ and $Av = 0$.

➤ Need to show that $u + v$ is in $\text{Nul}(A)$, i.e., that $A(u + v) = 0$. Using a property of matrix multiplication, compute

$$A(u + v) = Au + Av = 0 + 0 = 0$$

➤ Thus $u + v \in \text{Nul}(A)$, and $\text{Nul}(A)$ is closed under vector addition.

➤ Finally, if α is any scalar, then $A(\alpha u) = \alpha(Au) = \alpha(0) = 0$ which shows that αu is in $\text{Nul}(A)$.

➤ Thus $\text{Nul}(A)$ is a subspace of \mathbb{R}^n . ■

☐ See Example 1 in Sect. 4.2 of **text** [determining if a given vector belongs to $\text{Nul}(A)$]

☐ See Example 2 in Sect. 4.2 of **text** [determining a subspace by casting as a null space]

➤ Next we will see how to determine $\text{Nul}(A)$. See Example 3 of Sec. 4.2 of **text**. Details next.

- There is no obvious relation between vectors in $\text{Nul}(A)$ and the entries in A .
- We say that $\text{Nul}(A)$ is defined **implicitly**, because it is defined by a condition that must be checked.
- No explicit list or description of the elements in $\text{Nul}(A)$, so..
- ... we need to solve the equation $Ax = 0$ to produce an explicit description of $\text{Nul}(A)$.

Example: Find the null space of the matrix

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$$

- We will find a **spanning set** for $\text{Nul}(A)$.

11-13 Text: 4.2 – Vspaces2

11-13

Solution: first step is to find the general solution of $Ax = 0$ in terms of free variables. We know how to do this.

- Get reduced echelon form of augmented matrix $[A \ 0]$:

$$\begin{bmatrix} 1 & -2 & 0 & -1 & 3 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{array}{l} x_1 - 2x_2 - x_4 + 3x_5 = 0 \\ x_3 + 2x_4 - 2x_5 = 0 \\ 0 = 0 \end{array}$$

- x_2, x_4, x_5 are free variables, x_1, x_3 basic variables.
- For any selection of the free variables, can find a vector in $\text{Nul}(A)$ by computing x_1, x_3 in terms of these variables:

$$\begin{aligned} x_1 &= 2x_2 + x_4 - 3x_5 \\ x_3 &= -2x_4 + 2x_5 \end{aligned}$$

11-14 Text: 4.2 – Vspaces2

11-14

- OK - but how can we write these using spanning vectors (i.e. as linear combinations of specific vectors?)
- Solution - write x as:


$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_2 + x_4 - 3x_5 \\ x_2 \\ -2x_4 + 2x_5 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \underbrace{\begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_u + x_4 \underbrace{\begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}}_v + x_5 \underbrace{\begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}}_w$$


- General solution is of the form $x_2u + x_4v + x_5w$.
- Every linear combination of u, v , and w is an element of $\text{Nul}(A)$. Thus $\{u, v, w\}$ is a spanning set for $\text{Nul}(A)$, i.e.,

$$\text{Nul}(A) = \text{span}\{u, v, w\}$$


11-15 Text: 4.2 – Vspaces2

11-15

 Obtain the vector x of $\text{Nul}(A)$ corresponding to the choice: $x_2 = 1, x_4 = -2, x_5 = -1$. Verify that indeed it is in the null space, i.e., that $Ax = 0$

 For same example, find a vector in $\text{Nul}(A)$ whose last two components are zero and whose first component is 1. How many such vectors are there (zero, one, or infinitely many?)

Notes:

- 1. The spanning set produced by the method in the example is guaranteed to be linearly independent
-  Show this (proof by contradiction)
- 2. When $\text{Nul}(A)$ contains nonzero vectors, the number of vectors in the spanning set for $\text{Nul}(A)$ equals the number of free variables in the equation $Ax = 0$.

11-16 Text: 4.2 – Vspaces2

11-16

Column Space of a matrix

Definition: The column space of an $m \times n$ matrix A , written as $\text{Col}(A)$ (or $C(A)$), is the set of all linear combinations of the columns of A . If $A = [a_1 \cdots a_n]$, then

$$\text{Col}(A) = \text{span}\{a_1, \dots, a_n\}$$

Theorem: The column space of an $m \times n$ matrix A is a subspace of \mathbb{R}^m .

► A vector in $\text{Col}(A)$ can be written as Ax for some x [Recall that Ax stands for a linear combination of the columns of A].

That is: $\text{Col}(A) = \{b : b = Ax \text{ for some } x \text{ in } \mathbb{R}^n\}$

11-17

Text: 4.2 – Vspaces2

11-17

► The notation Ax for vectors in $\text{Col}(A)$ also shows that $\text{Col}(A)$ is the range of the linear transformation $x \rightarrow Ax$.

► The column space of an $m \times n$ matrix A is all of \mathbb{R}^m if and only if the equation $Ax = b$ has a solution for each b in \mathbb{R}^m

 Let

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}, \quad u = \begin{bmatrix} 3 \\ -2 \\ -1 \\ 0 \end{bmatrix}, \quad v = \begin{bmatrix} 3 \\ -1 \\ 3 \end{bmatrix}$$

a. Determine if u is in $\text{Nul}(A)$. Could u be in $\text{Col}(A)$?

b. Determine if v is in $\text{Col}(A)$. Could v be in $\text{Nul}(A)$?

11-18

Text: 4.2 – Vspaces2

11-18

► General remarks and hints:

1. $\text{Col}(A)$ is a subspace of \mathbb{R}^m [$m = 3$ in above example]
2. $\text{Nul}(A)$ is a subspace of \mathbb{R}^n [$n = 4$ in above example]
3. To verify that a given vector x belongs to $\text{Nul}(A)$ all you need to do is check if $Ax = 0$
4. To verify if $b \in \text{Col}(A)$ all you need to do is check if the linear system $Ax = b$ has a solution.

11-19

Text: 4.2 – Vspaces2

11-19