LINEAR EQATIONS [1.1] + (CONTINUED)

Gaussian Elimination

➤ Back to arbitrary linear systems.

<u>Principle of the method:</u> Since triangular systems are easy to solve, we will transform a linear system into one that is triangular. Main operation: combine rows so that zeros appear in the required locations to make the system triangular.

Recall Notation: Augmented form of a system

Main operation used: scaling and adding rows.

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Examples of such operations.

Example: Replace row 2 by: row 2 + row 1:

Example: Replace row 3 by: 2 times row 3 - row 1:

Example: Replace row 1 by: (0.5 * row 1)

Gaussian Elimination (cont.)

- \triangleright Go back to original system. Step 1 must eliminate x_1 from equations 2 and 3, i.e.,
- ➤ It must transform:

 $row_2 := row_2 - \frac{1}{2} \times row_1$: $row_3 := row_3 - \frac{1}{2} \times row_1$:

$$egin{bmatrix} 2 & 4 & 4 & 2 \ 0 & 1 & -1 & 0 \ 1 & 5 & 6 & -6 \ \end{bmatrix} \qquad egin{bmatrix} 2 & 4 & 4 & 2 \ 0 & 1 & -1 & 0 \ 0 & 3 & 4 & -1 \ \end{bmatrix}$$

Text: 1.1 - Gauss

Text: 1.1 - Gauss

➤ Step 2 must now transform:

$$row_3 := row_3 - 3 imes row_2 :
ightarrow egin{bmatrix} 2 & 4 & 4 & 2 \ 0 & 1 & -1 & 0 \ 0 & 0 & 7 & -7 \ \end{bmatrix}$$

ullet System is now triangular $\left\{egin{array}{ll} 2x_1+4x_2+4x_3=2\ x_2-x_3=0\ 7x_3=-7 \end{array}
ight.$

Find the solution of the above triangular system and verify that it is a solution of the original system

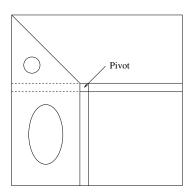
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 \rightarrow Solve

Gaussian Elimination: The algorithm

Recall: an algorithm is a sequence of operations (a 'recipe') to be performed by a computer.

- ➤ General step of Gaussian elimination :
- At step k subtract multiples of row k from rows $k+1, k+\frac{\text{Row }k}{2, \cdots, n}$ in order to zero-out entries below a_{kk} in column k.
- Repeat this step for k = 1, 2, ..., n 1



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Step k in words:

for each row i where i runs from i = k+1 to i = n do: subtract piv * row k from row i (where $piv = a_{ik}/a_{kk}$).

ALGORITHM: 1. Gaussian Elimination

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1. For k = 1: n - 1 Do:

2. For i = k + 1: n Do:

3. piv := a_{ik}/a_{kk}

4. For j := k + 1: n + 1 Do:

5. a_{ij} := a_{ij} - piv * a_{kj}

6. End

7. End
```

Matlab Script:

```
function [x] = gauss (A, b)
% function [x] = gauss (A, b)
% solves A x = b by Gaussian elimination
n = size(A,1);
A = [A,b];
for k=1:n-1
    for i=k+1:n
        piv = A(i,k) / A(k,k);
        A(i,k+1:n+1)=A(i,k+1:n+1)-piv*A(k,k+1:n+1);
    end
end
x = backsolv(A,A(:,n+1));
```

- \blacktriangleright Input: matrix A and right-hand side b. Output: solution x.
- ➤ Invokes backsolv.m to solve final triangular system.

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Text: 1.1 – Gauss

Gaussian Elimination: Pivoting

Consider again Gaussian Elimination for the linear system

$$\left\{ \begin{array}{llll} 2x_1 + 2x_2 + 4x_3 = & 2 \\ x_1 \ + \ x_2 \ + \ x_3 \ = & 1 \\ x_1 \ + \ 4x_2 + 6x_3 = & -5 \end{array} \right. \text{ Or: } \left[\begin{array}{lll} 2 & 2 & 4 & 2 \\ 1 & 1 & 1 & 1 \\ 1 & 4 & 6 & -5 \end{array} \right]$$

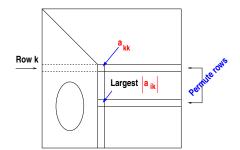
 $row_2 := row_2 - \frac{1}{2} \times row_1$: $row_3 := row_3 - \frac{1}{2} \times row_1$:

ightharpoonup Pivot a_{22} is zero. Solution : permute rows 2 and 3 \longrightarrow

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Gaussian Elimination: Partial Pivoting



General situation

 \triangleright Partial Pivoting: *Always* Permute row k with row l such that

$$|a_{lk}| = \max_{i=k,...,n} |a_{ik}|$$

➤ More 'stable' algorithm.

Wiore stuble digorithm.

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Gauss-Jordan Elimination

Principle of the method: We will now transform the system into one that is even easier to solve than a triangular system, namely a diagonal system. The method is very similar to Gaussian Elimination. It is just a bit more expensive.

Back to original system (P. 2-2). Step 1 must transform:

➤ Same step as 1st step of Gaussian Elimination.

 $row_2 := row_2 - 0.5 \times row_1$: $row_3 := row_3 - 0.5 \times row_1$:

$$egin{bmatrix} 2 & 4 & 4 & 2 \ 0 & 1 & -1 & 0 \ 1 & 5 & 6 & -6 \ \end{bmatrix}$$

$$\begin{bmatrix} 2 & 4 & 4 & 2 \\ 0 & 1 & -1 & 0 \\ 0 & 3 & 4 & -7 \end{bmatrix}$$

Must now transform:

$$egin{bmatrix} 2 & 4 & 4 & 2 \ 0 & 1 & -1 & 0 \ 0 & 3 & 4 & -7 \ \end{bmatrix}$$
 into: $egin{bmatrix} x \ 0 \ 0 \ \end{bmatrix}$

to:
$$\begin{vmatrix} x & 0 & x | x \\ 0 & x & x | x \\ 0 & 0 & x | x \end{vmatrix}$$

 $row_1 := row_1 - 4 \times row_2$: $row_3 := row_3 - 3 \times row_2$:

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There is now a third step:

$$row_1 := row_1 - \frac{8}{7} \times row_3$$
: $row_2 := row_2 - \frac{-1}{7} \times row_3$:

$$\begin{bmatrix} 2 & 0 & 0 & 10 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 7 & -7 \end{bmatrix}$$

$$\begin{array}{c|ccccc} 2 & 0 & 0 & 10 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 7 & -7 \end{array}$$

Text: 1.1-.2 - GaussJordan

$$\left\{egin{array}{lll} 2x_1&=10\ x_2&=-1\ 7x_3=-7 \end{array}
ight. egin{array}{lll} ext{Solution:} &x_1=5\ x_2=-1\ x_3=-1 \end{array}
ight.$$

3-13 Text: 1.1-.2 – GaussJordan

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Gauss-Jordan - variants

Common variant: Before an elimination step is started divide the row by diagonal entry a_{kk}

- \blacktriangleright At the end all diagonal entries are ones \rightarrow solution = rhs
- Redo the previous example with this variant.
- Is this more or less costly than the original method?

NOTE: unless otherwise specified Gauss-Jordan will refer to this scaled version.

➤ Also: Pivoting can be implemented just like Gaussian elimination.

Important: Never swap a pivot row with a row above it! (destroys structure)

3-14 Text: 1.1-.2 – GaussJordan

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Linear systems – summary of complexity results

ightharpoonup The number of operations needed to solve a triangular linear system with n unknowns is

$$C_T(n) = n^2$$

The number of operations required to solve a linear system with n unknowns by Gaussian elimination is

$$C_G(n)pprox rac{2}{3}n^3$$

The number of operations required to solve a linear system with *n* unknowns by Gauss-Jordan elimination is

$$C_{GJ}(n) pprox n^3$$

Note: remember that Gauss-Jordan costs 50% more than Gauss.

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