

Matlab script gauss.m: a few explanations

```
function [x] = gauss (A, b)
% function [x] = gauss (A, b)
% solves A x = b by Gaussian elimination
n = size(A,1) ;
A = [A,b];
for k=1:n-1
    for i=k+1:n
        piv = A(i,k) / A(k,k) ;
        A(i,k+1:n+1)=A(i,k+1:n+1)-piv*A(k,k+1:n+1);
    end
end
x = backsolv(A,A(:,n+1));
```

Function function [x] = gauss (A, b)
 % function [x] = gauss (A, b)
 % solves A x = b by Gaussian elimination
 ...

4-1 Text: 1.1 – MLgauss

4-1

- The file containing the above script should be called gauss.m.
- The syntax for function is simple:

```
function [Output-args] = func-name(Input-args)
% lines of comments
```

- Takes input arguments. Computes some values and returns them in the output arguments.

➤ The gauss.m script has 2 input arguments (A and b) and one output argument (x)

- % indicates a commented line. First few lines of comments after function header are echoed when you type

>> help func-name For example >> help gauss

4-2 Text: 1.1 – MLgauss

4-2

```
n = size(A,1) ;      % <-- n=Number of rows in matrix
A = [A,b];          % <-- Adds b as last column of A
                   % Now A contains augmented system.
                   % It has size n x (n+1)
```

```
for k=1:n-1          % Main loop in GE -- for each k
    for i=k+1:n      % sweep rows i=k+1 to i=n
        ...commands % these commands will each combine
    end              % row i with a multiple of row k
end
```

Example: Step $k = 3$ ($n = 6$)

```
for i=4:6
    piv=a(i,3)/a(3,3);
    row_i=row_i-piv*row_3;
end
```

*	*	*	*	*	*	*
0	*	*	*	*	*	*
0	0	*	*	*	*	*
0	0	*	*	*	*	*
0	0	*	*	*	*	*
0	0	*	*	*	*	*

4-3 Text: 1.1 – MLgauss

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```
piv = A(i,k) / A(k,k) ;
A(i,k+1:n+1)=A(i,k+1:n+1)-piv*A(k,k+1:n+1);
```

➤ The above: 1) computes the multiplier (pivot) to use in the elimination; 2) combines rows. Result = a zero in position (i, k) .

➤ When combining row i with row k no need to deal with zeros in columns 1 to $k - 1$. Result will be zero.

➤ Also we know $A(i, k)$ will be zero – can be skipped.

➤ Result: need to combine rows from positions $k + 1$ to $n + 1$.

```
x = backsolv(A,A(:,n+1));
```

➤ The above invokes the back-solve script to solve the final system

4-4 Text: 1.1 – MLgauss

4-4

THE ECHELON FORM [1.2]

The standard echelon form

A rectangular matrix is in **echelon form** (or **row echelon form**) if it has the following three properties:

1. All nonzero rows are above any rows of all zeros.
2. Each leading entry of a row is in a column to the right of the leading entry of the row above it.
3. All entries in a column below a leading entry are zeros.

➤ Each ■ is a **nonzero** (leading) entry.

➤ A * can be a non-zero or a zero entry.

$$\begin{bmatrix} \blacksquare & * & * & * & * & * & * & * & * & * & * \\ 0 & 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

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Text: 1.2 – Echln

4-6

 Which of these matrices is in Row Echelon Form? [* = nonzero]

$$\begin{bmatrix} * & * & * & * & * & * & * & * & * & * & * \\ 0 & 0 & * & * & * & * & * & * & * & * & * \\ 0 & 0 & * & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{bmatrix} * & * & * & * & * & * & * & * & * & * & * \\ 0 & 0 & * & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & * & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & * & * & * & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{bmatrix} * & * & * & * & * & * & * & * & * & * & * \\ 0 & 0 & * & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & * & * & * & * & * \\ 0 & * & 0 & 0 & 0 & 0 & 0 & 0 & 0 & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

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Text: 1.2 – Echln

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➤ A sort of 'stretched' (to the right) upper triangular form with structure of some columns repeated

➤ Ignore the formal definition for a moment - use intuition from Gaussian Elimination. Example:

$$\begin{bmatrix} 1 & -1 & 2 & -1 & 2 \\ 2 & -2 & 3 & -1 & 4 \\ 3 & -3 & 9 & -6 & 6 \end{bmatrix}$$

➤ 1st step of Gaussian Elimination yields:

$$\begin{bmatrix} 1 & -1 & 2 & -1 & 2 \\ 0 & \underline{0} & \underline{-1} & 1 & 0 \\ 0 & \underline{0} & 3 & -3 & 0 \end{bmatrix}$$

← a_{22} is zero and pivoting does not help. Skip & go to 3rd column where $a_{23} = -1$:

➤ GE on rows 2 & 3:

➤ $row_3 := row_3 - (-3) * row_2$

Result: →

$$\begin{bmatrix} 1 & -1 & 2 & -1 & 2 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

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Text: 1.2 – Echln

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In words: Row Echelon algorithm is a variant of Gaussia Elimination (with pivoting).

* Step k now has two indices: pivot row k and pivot column l . (At the start $k = 1, l = 1$.)

* Step k : Try to eliminate entries $a_{k+1,l}, a_{k+2,l}, \dots, a_{m,l}$.

* Do pivoting if necessary and try perform Gaussian Elimination.

* If the sub-column is all zero, set $l := l + 1$ and repeat.

	l				
k	*	*	*	*	*
	0	0	0	*	*
	0	0	*	*	*
	0	0	*	*	*

Case 1: swap row 2 and 3 (or 4). Then do GE step.

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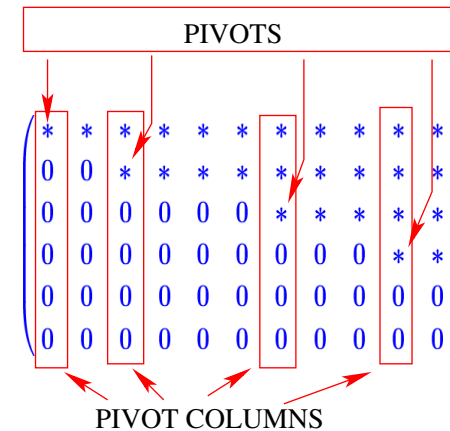
			$l \quad l_{new}$		
		*	*	*	*
k	0	0	0	*	*
	0	0	0	*	*
	0	0	0	*	*
	0	0	0	*	*

Case 2: Reset l to $l = 4$. Continue.

Text: 1.2 – Echln

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Terminology: Pivots, and pivot columns



➤ Important in capturing the span of the columns of A (called the **range** of A - to be covered in detail later)

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Text: 1.2 – Echln

4-10

The reduced row echelon form

Definition : A matrix is in **reduced echelon form** (or **reduced row echelon form**) if: Matlab: rref

[1–3] It is in echelon form and, in addition,

4. The leading entry in each nonzero row is 1.

5. Each leading 1 is the only nonzero entry in its column.

$$\begin{bmatrix} 1 & * & 0 & * & * & 0 & * & * & 0 & * \\ & 1 & * & * & * & 0 & * & * & 0 & * \\ & & & 1 & * & * & 0 & * & & \\ & & & & & & 1 & * & & \end{bmatrix}$$

How would you obtain the rref from the standard echelon form?

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Text: 1.2 – Echln

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➤ Any nonzero matrix may be row reduced (i.e., transformed by elementary row operations) into more than one matrix in echelon form, using different sequences of row operations.

➤ However, the reduced echelon form one obtains from a matrix is unique:

Each matrix is row equivalent to one and only one reduced echelon matrix.

➤ Remember that the permissible row operations are:

1) Interchange; 2) addition; 3) scaling.

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Text: 1.2 – Echln

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Pivot position

- A **pivot position** in a matrix A is a location in A that corresponds to a leading 1 in the reduced echelon form of A . A pivot column is a column of A that contains a pivot position.

$$\begin{bmatrix} \boxed{1} & * & 0 & * & * & * & 0 & * & * & 0 & * \\ & & \boxed{1} & * & * & * & 0 & * & * & 0 & * \\ & & & & & & \boxed{1} & * & * & 0 & * \\ & & & & & & & & & \boxed{1} & * \end{bmatrix}$$

- In this example, the pivot columns are 1, 3, 7, and 10
-  Find out how to get the pivot positions from matlab's rref

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Text: 1.2 – Echln

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Example with standard echelon Form

- Example:** Row reduce the matrix A below to echelon form, and locate the pivot columns of A .

$$\begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

- Solution:** The top of the leftmost nonzero column is the first pivot position. A nonzero entry, or pivot, must be placed in this position.

- Interchange rows 1 and 4 (note: in reality it is preferable to interchange rows 1 and 3. Why?)

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Text: 1.2 – Echln

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↓ Pivot

$$\begin{bmatrix} \boxed{1} & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

↑ Pivot Column

- Create zeros below the pivot, 1, by adding multiples of the first row to the rows below → Next matrix:

$$\begin{bmatrix} \boxed{1} & 4 & 5 & -9 & -7 \\ 0 & \boxed{2} & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -13 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

↑

Next pivot column

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Text: 1.2 – Echln

4-15

- Next pivot column: Add $-5/2$ times row 2 to row 3, and add $3/2$ times row 2 to row 4.

Result: →

$$\begin{bmatrix} \boxed{1} & 4 & 5 & -9 & -7 \\ 0 & \boxed{2} & 4 & -6 & -6 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -5 & 0 \end{bmatrix}$$

- Can't create a leading entry in column 3 → Move to col. 4. Swap rows 3 & 4. Done.
- Pivot columns: 1, 2, and 4.

$$\begin{bmatrix} \boxed{1} & 4 & 5 & -9 & -7 \\ 0 & \boxed{2} & 4 & -6 & -6 \\ 0 & 0 & 0 & \boxed{-5} & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- Recall: Algorithm to get **standard** row echelon form is a form of Gaussian elimination with pivoting
- Algorithm to get **reduced** row echelon form is a form of Gauss-Jordan elimination with pivoting
- Next: same example done with reduced form

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Text: 1.2 – Echln

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Same example with reduced echelon Form

- Initial matrix below. First step same: swap rows 1 & 4

$$\begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

- Next: Create zeros below the pivot, 1, by adding multiples of the first row to the rows below it.

→ Next matrix:

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

- Scale 2nd row:

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 1 & 2 & -3 & -3 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

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Text: 1.2 – Echln

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- Next step: create zeros in column 2 [except position (2,2)]
- Move l to column 4; Swap rows 4, 5;

$$\begin{bmatrix} 1 & 0 & -3 & 3 & 5 \\ 0 & 1 & 2 & -3 & -3 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -5 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -3 & 3 & 5 \\ 0 & 1 & 2 & -3 & -3 \\ 0 & 0 & 0 & -5 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Scale row 3

- Finally: create zeros in column 4 except position (3,4).

$$\begin{bmatrix} 1 & 0 & -3 & 3 & 5 \\ 0 & 1 & 2 & -3 & -3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -3 & 0 & 5 \\ 0 & 1 & 2 & 0 & -3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- Pivot positions: 1, 2, 4. They are (always) identical with those obtained from Standard Row Echelon form.

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Text: 1.2 – Echln

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APPLICATIONS OF THE ECHELON FORM [1.3]

Solving a general linear system

Question: What are **all** the solutions of a linear system $[A, b]$

- Recall that we have 3 scenarios: 1) 0 solution; 2) infinitely many sols.; 3) exactly one solution.
- Set is called “general solution” or “complete solution”
- Answer provided by echelon form [reduced or standard]

Step 1 Form the augmented system $[A, b]$

$$\begin{bmatrix} * & * & * & * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * & * & * & * \end{bmatrix}$$

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Text: 1.3 – Echln2

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- Step 2** Obtain the reduced echelon form.
- Result is something like:

$$\begin{array}{cccccccccccc|c} 1 & * & 0 & * & * & * & 0 & * & * & 0 & * & \\ & & 1 & * & * & * & 0 & * & * & 0 & * & \\ & & & & & & 1 & * & * & 0 & * & \\ & & & & & & & & & & 1 & * \end{array}$$

Important: Solutions to this system same as those of $[A, b]$. So we'll find the solutions from this reduced system

✎ What can you say if the last column (RHS) happens to be a pivot column?

- Unknowns associated with pivots are called **basic**
- Others are called **free**
- In above example: 1, 3, 7, 10 are **basic**, 2, 4, 5, 6, 8, 9, are **free**, and column 11 is the RHS (not a variable).

Step 3 Write solutions: solutions depend on parameters which are the free variables.

- Express basic variables in terms of the free variables
- For any values given to the free variables you will get a solution
- For example for the above picture: $x_{10} = b_4$; $x_7 = b_3 - \text{scalar} \cdot x_8 - \text{scalar} \cdot x_9$ etc..

✎ Find **general solution** when augmented matrix is:

$$\begin{array}{ccccccc|c} 1 & 2 & 0 & 0 & 1 & 0 & 0 & -2 \\ 1 & 2 & -1 & -2 & 2 & 2 & 3 & -3 \\ 1 & 2 & 2 & 4 & -3 & -4 & -4 & -6 \\ 0 & 0 & 1 & 2 & -3 & 0 & -5 & -3 \\ 1 & 2 & 0 & 0 & 2 & 0 & -1 & 1 \end{array}$$

- Get the reduced echelon form [use matlab!]

$$\begin{array}{ccccccc|c} \boxed{1} & 2 & 0 & 0 & 0 & 0 & 1 & -5 \\ 0 & 0 & \boxed{1} & 2 & 0 & 0 & -8 & 6 \\ 0 & 0 & 0 & 0 & \boxed{1} & 0 & -1 & 3 \\ 0 & 0 & 0 & 0 & 0 & \boxed{1} & -2 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array}$$

- (1): $x_1 + 2x_2 + x_7 = -5$
- (2): $x_3 + 2x_4 - 8x_7 = 6$
- (3): $x_5 - x_7 = 3$
- (4): $x_6 - 2x_7 = 1$
- (5): $0 = 0$ (vacuous)

→

- Basic variables:
1, 3, 5, 6
- Free variables:
2, 4, 7
- Right-hand side : 8

$$\begin{array}{l} x_1 = -5 - 2x_2 - x_7 \\ x_3 = 6 - 2x_4 + 8x_7 \\ x_5 = 3 + x_7 \\ x_6 = 1 + 2x_7 \end{array}$$

Note: It is also possible to use the standard (non-reduced) row-echelon form - Requires back substitution. Result is the same.

✎ What if last component of RHS is zero (i.e., $A(5, 8) = 0$)

✎ Below is the **standard** echelon form for the previous example. Find all solutions.

$$\begin{array}{ccccccc|c} 1 & 2 & 0 & 0 & 1 & 0 & 0 & -2 \\ 0 & 0 & 2 & 4 & -4 & -4 & -4 & -4 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 & -3 \\ 0 & 0 & 0 & 0 & 0 & 2 & -4 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array}$$

- ✎ Find all solutions for which x_4 and x_7 are zero.
- ✎ Among these find all solutions for which x_1 is zero.

✎ We seek 5 numbers x_1, \dots, x_5 such that their sum is 50, the sum of 3 of them (e.g. the odd-labeled ones) is 25, and the difference between the other 2 is 5. Write the equations to be satisfied and find the general solution.