

GRAPH LAPLACEANS AND THEIR APPLICATIONS

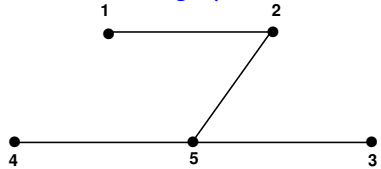
- Graph Laplaceans, definitions and basic properties
- Graph partitioning –
- Introduction to clustering
- Graph Embeddings, vertex embeddings . The problem
- Use of Graph Laplaceans, Laplacean Eigenmaps
- Use of similarity graphs: Locally Linear Embeddings
- Explicit dimension reduction method: PCA, LLP, ...

➤ Simplest case:

$$w_{ij} = \begin{cases} 1 & \text{if } (i, j) \in E \text{ and } i \neq j \\ 0 & \text{else} \end{cases} \quad D = \text{diag} \left[d_i = \sum_{j \neq i} w_{ij} \right]$$

Example:

Consider the graph



$$L = \begin{bmatrix} 1 & -1 & 0 & 0 & 0 \\ -1 & 2 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & -1 & -1 & -1 & 3 \end{bmatrix}$$

Graph Laplaceans - Definition

➤ “Laplace-type” matrices associated with general undirected graphs – useful in many applications

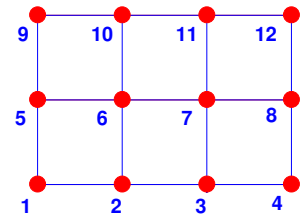
➤ Given a graph $G = (V, E)$ define

- A matrix W of weights w_{ij} for each edge
- Assume $w_{ij} \geq 0$, $w_{ii} = 0$, and $w_{ij} = w_{ji} \forall (i, j)$
- The diagonal matrix $D = \text{diag}(d_i)$ with $d_i = \sum_{j \neq i} w_{ij}$

➤ Corresponding **graph Laplacean** of G is: $L = D - W$

➤ Gershgorin's theorem $\rightarrow L$ is positive semidefinite.

1. Define the graph Laplacean for the graph associated with the simple mesh shown next. [use the simple weights of 0 or 1]. What is the difference with the discretization of the Laplace operator for case when mesh is the same as this graph?



Proposition:

- (i) L is symmetric semi-positive definite.
- (ii) L is singular with $\mathbf{1}$ as a null vector.
- (iii) If G is connected, then $\text{Null}(L) = \text{span}\{\mathbf{1}\}$
- (iv) If G has $k > 1$ connected components G_1, G_2, \dots, G_k , then the nullity of L is k and $\text{Null}(L)$ is spanned by the vectors $z^{(j)}$, $j = 1, \dots, k$ defined by:

$$(z^{(j)})_i = \begin{cases} 1 & \text{if } i \in G_j \\ 0 & \text{if not.} \end{cases}$$

A few properties of graph Laplaceans

Define: oriented incidence matrix H : (1) First orient the edges $i \sim j$ into $i \rightarrow j$ or $j \rightarrow i$. (2) Rows of H indexed by vertices of G . Columns indexed by edges. (3) For each (i, j) in E , define the corresponding column in H as $\sqrt{w(i, j)}(e_i - e_j)$.

Example: In previous example (4 p. back) orient $i \rightarrow j$ so that $j > i$ [lower triangular matrix representation]. Then matrix H is:

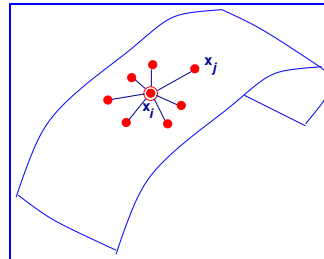
$$H = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & -1 & -1 & -1 \end{bmatrix}$$

Property 1 $L = HH^T$

Ex 2 Re-prove part (iv) of previous proposition by using this property.

Proof: (i) and (ii) seen earlier and are trivial. (iii) Clearly $u = \mathbf{1}$ is a null vector for L . The vector $D^{-1/2}u$ is an eigenvector for the matrix $D^{-1/2}LD^{-1/2} = I - D^{-1/2}WD^{-1/2}$ associated with the smallest eigenvalue. It is also an eigenvector for $D^{-1/2}WD^{-1/2}$ associated with the largest eigenvalue. By the Perron Frobenius theorem this is a simple eigenvalue... (iv) Can be proved from the fact that L can be written as a direct sum of the Laplacian matrices for G_1, \dots, G_k . ■

A few properties of graph Laplaceans



Strong relation between $x^T Lx$ and local distances between entries of x
 ► Let $L =$ any matrix s.t. $L = D - W$, with $D = \text{diag}(d_i)$ and

$$w_{ij} \geq 0, \quad d_i = \sum_{j \neq i} w_{ij}$$

Property 2: for any $x \in \mathbb{R}^n$:

$$x^T Lx = \frac{1}{2} \sum_{i, j} w_{ij} |x_i - x_j|^2$$

Property 3: (generalization) for any $Y \in \mathbb{R}^{d \times n}$:

$$\text{Tr}[YLY^T] = \frac{1}{2} \sum_{i,j} w_{ij} \|y_i - y_j\|^2$$

► Note: $y_j = j$ -th column of Y . Usually $d < n$. Each column can represent a data sample.

Property 4: For the particular $L = I - \frac{1}{n} \mathbb{1} \mathbb{1}^T$

$$XLX^T = \bar{X} \bar{X}^T == n \times \text{Covariance matrix}$$

Property 5: L is singular and admits the null vector

$\mathbb{1} = \text{ones}(n, 1)$

► Would like to minimize (Lx, x) subject to $x \in \{-1, 1\}^n$ and $e^T x = 0$ [balanced sets]

► Will solve a relaxed form of this problem

Ex 3 What if we replace x by a vector of ones (representing one partition) and zeros (representing the other)?

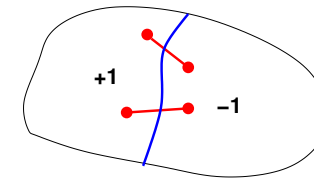
Ex 4 Let x be any vector and $y = x + \alpha \mathbb{1}$ and L a graph Laplacean. Compare (Lx, x) with (Ly, y) .

Property 6: (Graph partitioning) Consider situation when $w_{ij} \in \{0, 1\}$. If x is a vector of signs (± 1) then

$$x^T Lx = 4 \times (\text{number of edge cuts})$$

edge-cut = pair (i, j) with $x_i \neq x_j$

► Consequence: Can be used to partition graphs



► Consider any symmetric (real) matrix A with eigenvalues $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$ and eigenvectors u_1, \dots, u_n

► Recall that:
(Min reached for $x = u_1$)

$$\min_{x \in \mathbb{R}^n} \frac{(Ax, x)}{(x, x)} = \lambda_1$$

► In addition:
(Min reached for $x = u_2$)

$$\min_{x \perp u_1} \frac{(Ax, x)}{(x, x)} = \lambda_2$$

► For a graph Laplacean $u_1 = \mathbb{1}$ = vector of all ones and

► ...vector u_2 is called the Fiedler vector. It solves a **relaxed** form of the problem -

$$\min_{x \in \{-1,1\}^n; \mathbb{1}_{x=0}} \frac{(Lx, x)}{(x, x)}$$

→

$$\min_{x \in \mathbb{R}^n; \mathbb{1}_{x=0}} \frac{(Lx, x)}{(x, x)}$$

► Define $v = u_2$ then $lab = \text{sign}(v - \text{med}(v))$

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– Glaplacians

Three approaches to graph partitioning:

1. Spectral methods - Just seen + add Recursive Spectral Bisection.
2. Geometric techniques. Coordinates are required. [Houstis & Rice et al., Miller, Vavasis, Teng et al.]
3. Graph Theory techniques – multilevel,... [use graph, but no coordinates]
 - Currently best known technique is Metis (multi-level algorithm)
 - Simplest idea: Recursive Graph Bisection; Nested dissection (George & Liu, 1980; Liu 1992)
 - Advantages: simplicity – no coordinates required

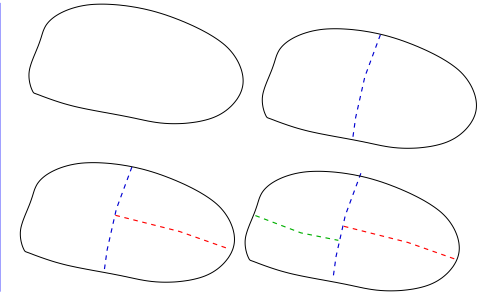
 Run `testBis_simple` and `testMeshPart` in matlab class site

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Recursive Spectral Bisection

- 1 Form graph Laplacean
- 2 Partition graph in 2 based on Fiedler vector
- 3 Partition largest subgraph in two recursively ...
- 4 ... Until the desired number of partitions is reached



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Example of a graph theory approach

- Level Set Expansion Algorithm
- Given: p nodes ‘uniformly’ spread in the graph (roughly same distance from one another).
- Method: Perform a level-set traversal (BFS) from each node simultaneously.
- Best described for an example on a 15×15 five – point Finite Difference grid.
- See [Goehring-YS '94, See Cai-YS '95]
- Approach also known under the name ‘bubble’ algorithm and implemented in some packages [Party, DibaP]

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